



SP+ The New Generation

Low-Backlash Planetary Gearhead

2005 - V



alpha

a WITTENSTEIN AG company

SP⁺ a step, a leap... You decide!

alpha's customers worldwide have come to expect that we set the pace for innovations. The time has come for the **SP** to step down for its successor: **SP⁺**. The ⁺ marks the new era of Low-Backlash Planetary Gearheads, in both cyclic and continuous duty operations.

What created this new benchmark product?

Its special characteristics, individually exciting, but together unique.

- Higher acceleration and output torques.
- Low standard backlash, optional < 1 arcmin.
- Improved output bearings for higher axial and radial loading capacities.
- 4 times quieter than the already quiet **SP**.
- Wide variety of available ratios, incl. binary.
- New proprietary shaft seals for IP65 protection.
- 100% quality testing prior to shipping.
- The only gearhead backed by a 20 year history of design and manufacturing innovations.



But that is not enough

SP⁺ features a positioning accuracy and impressive acceleration torques that previously were possible only with the alpha TP series. It has a markedly higher torsional stiffness and service life than competitive products. It can be flawlessly mounted to the motor in one single step. You'll be pleased not only as an engineer, but also as a business man, in demanding the highest in efficiency, productivity and process reliability.

Again alpha has converted its years of experience in gearhead design and manufacturing, with the **SP⁺** product taking performance and reliability to a new level of excellence.



SP+ - displays real character

Higher power density

Although its predecessor, the **SP**, already delivers exceptional performance, we have managed to increase the maximum acceleration torque of the **SP+** even further.

Any mounting position

Regardless of how your **SP+** is mounted, it always has the same amount of oil, eliminating the need to specify mounting position when ordering. Thus flexibility of machine mounting orientation is possible with one ordering code.

Motor mounting: Simply child's play

The motor can be accurately mounted in just one step, therefore mounting errors are impossible.

This patented alpha motor mount is also available with optional integrated linear length compensation.



Cutting edge innovations made by alpha

We have been developing, manufacturing and distributing low-backlash planetary gearheads, servo right-angled gearheads, complete drive units and planetary elevator machines with an integrated servo motor since 1984.

Profit from our comprehensive service package: from individual components to complete systems, supported by our competent engineering services, several hundred employees worldwide are committed to our cause with operations in the US, UK, France, Italy, Belgium and Japan. alpha's headquarters are on the "Romantic Road" in Igersheim / Germany.

alpha is a member of the **WITTENSTEIN AG** Group which has rightly established a name for itself with numerous innovations in industries such as aerospace and simulation, medical technology, elevator drives and Formula One racing.



Helical gearing delivers: Smooth, quiet running

SP+ whispers. The noise emission of the **SP+** is 6 dB(A) lower than that of our already quiet SP line, making the **SP+** four times quieter. What's more, vibration is dramatically reduced allowing smooth running for you.

Highest positioning accuracy

You know the classic precision of **SP** – now **SP+** provides a new world of precision. We have reduced the torsional backlash and can now offer you less than one arc minute of backlash on request, dramatically increasing positioning accuracy.

World-class lifespan

alpha's proprietary new seals for the **SP+** optimise both material and geometry, to provide true IP65 protection. In addition, the output bearing capacity has been improved to surpass anything in its class, giving the **SP+** a world-class lifespan.

Leaders of the pack

We are driven by a desire to enhance our customers' success with products and systems from alpha. We set benchmarks when it comes to precision, performance and durability. Our trailblazing technology gives our customers an edge in their respective market sectors. Place your trust in premium quality and total reliability from alpha. Choose world class engineering – the foundation for strong partnerships and added value that is passed on to your customers.

alpha benefits at a glance:

- **Record-breaking lifespan**
Extremely long service life resulting from intelligent design, latest synthetic lubrication technology, exclusive sealing technology, and incredibly strong output bearings.
- **Motor mounting is almost foolproof**
Simple and reliable mounting in a single step.
- **Top quality from alpha**
In-house development and manufacture of all products combined with a pioneering spirit and an insatiable urge to improve.



alpha

SP+ High Speed® stays cool

The trend is clear. Low-Backlash gearheads are being increasingly implemented in continuous duty operations at high speeds. This applies especially to the packaging, printing, textile, paper and semiconductor industries, but also in newly emerging markets of glass, food and hygiene products.

Gearheads that run around the clock literally must stay cool.

SP High Speed showed that was possible. **SP+ High Speed** will continue the success story.

Like its predecessor, the **SP+ High Speed** provides superior performance. It can be run continuously with a long service life. It gets no more than lukewarm even under highest stress, and it incurs no maintenance or service costs.

Achieving 99.9 percent reliability, while cooling the motor and increasing efficiency, has earned us the right to be called masters in our field.

SP+ accelerates with the new alpha speedline®

If your production process can't wait, why not order **SP+** with alpha's popular speedline service? Dispatch from our factory is guaranteed within a mere 24 or 48 hours.

Ask for more information about alpha speedline.
We look forward to speeding up delivery for you.





SP+® choosing correctly is so simple

SP+ for cyclic operation or SP+ High Speed for continuous operation

On each of the subsequent double-page spreads we introduce one **SP+ / SP+ High Speed** series. The left page contains the dimensions and drawings, the right page contains a table with technical data, ratios and the most important characteristic values. The data is listed separately for MF (**SP+**) and MC (**SP+ High Speed**) versions, one stage and two stages respectively.

As always, your personal alpha engineer is always available for a technical discussion.

Choose **MF (SP+)** for **cyclic operation S5**, where duty cycle is <60% and <20 minutes.

Choose **MC (SP+ High Speed)** for **continuous operation S1**, where duty cycle >60% or >20 minutes.

These guidelines cover most applications. Please contact alpha in special situations.

Ask for the SP+, the new quiet star of the Low-Backlash Planetary Gearhead universe.

SP+ Gearheads: Fast selection

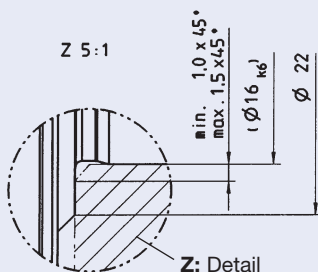
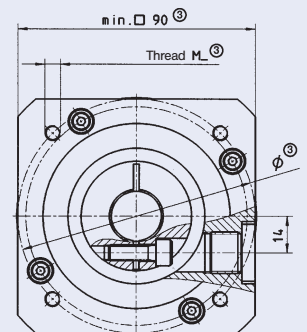
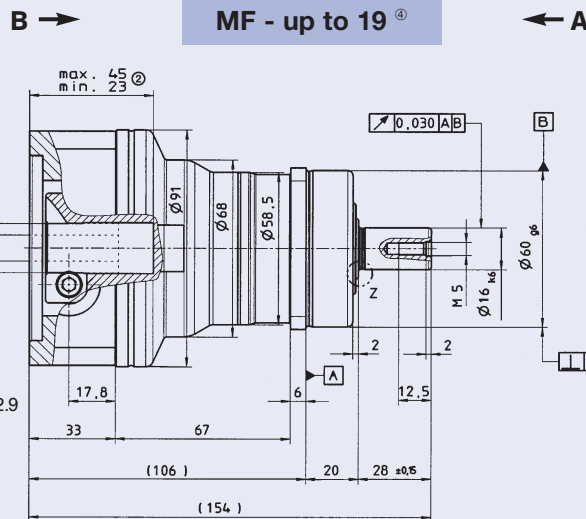
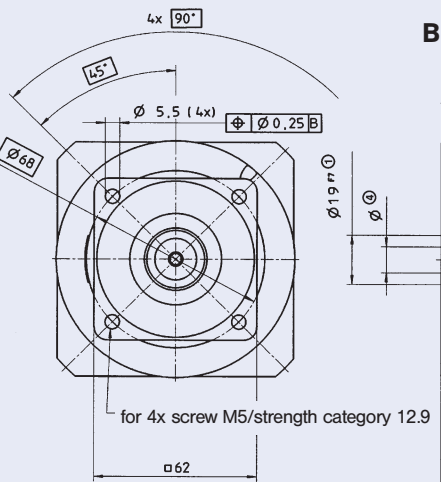
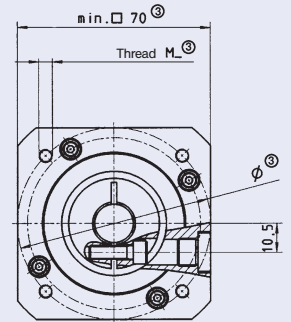
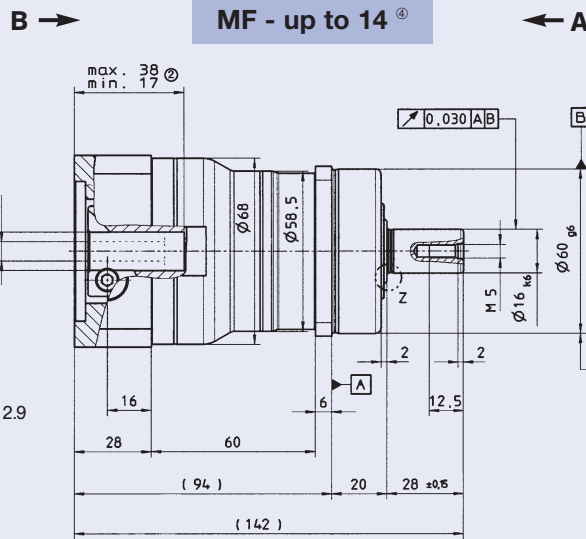
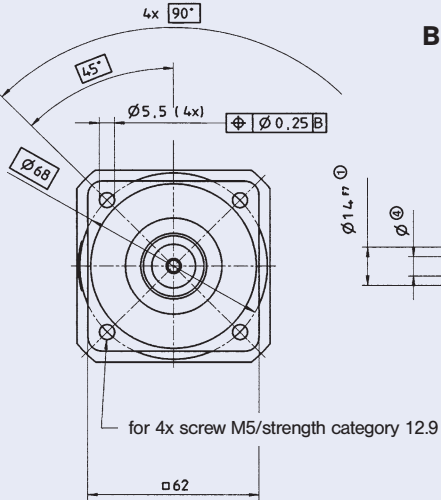
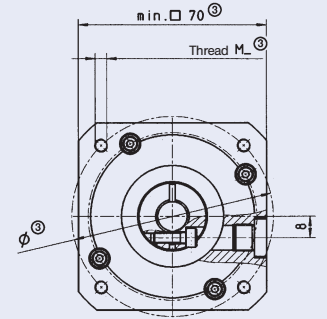
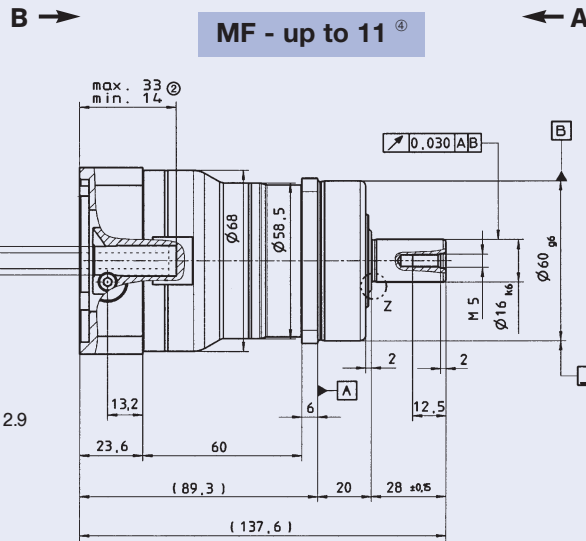
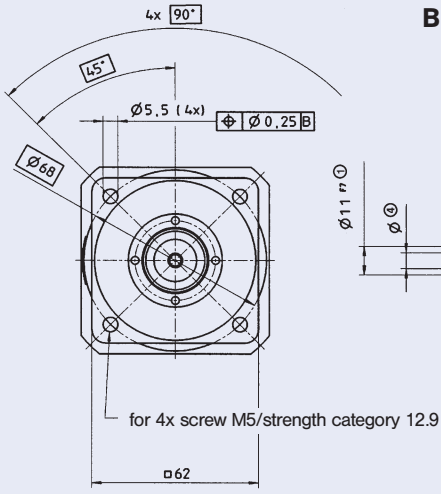
Size			060		075		100		140	
			MF		MF	MC	MF	MC	MF	MC
Maximum acceleration torque	T_{2B}	Nm	30-40		85-110	42-66	225-300	100-165	390-600	195-330
Nominal output torque	T_{2N}	Nm	17-26		47-75	26-42	120-180	65-105	200-360	120-210
Emergency stop torque	T_{2NOT}	Nm	80-100		200-250		500-625		1000-1250	
Maximum input speed	n_{1Max}	min ⁻¹	6000		6000	6000	4500	6000	4000	6000
Nominal input speed	n_{1N}	min ⁻¹	3300 - 5500		2900 - 4500	4500	2500 - 4200	3500-4500	2100-3900	3000-4500
Page			8 - 11		12 - 15		16 - 19		20 - 23	

Size			180		210 classic		240 classic	
			MF	MC	MF	MC	MF	MC
Maximum acceleration torque	T_{2B}	Nm	880-1100	275-485	1520-1900	400-750	2720-3400	670-1200
Nominal output torque	T_{2N}	Nm	530-750	170-305	1000	260-480	1700	430-800
Emergency stop torque	T_{2NOT}	Nm	2200-2750		3800-4750		6800-8500	
Maximum input speed	n_{1Max}	min ⁻¹	3500-4000	4500-6000	2500-3500	3400-6000	2200-3500	3400-5000
Nominal input speed	n_{1N}	min ⁻¹	1500-3400	3000-4500	1200-2900	3000-4500	1000-2400	3000-4000
Page			24 - 27		30 - 34		30 - 34	

View A

Motor shaft diameter (mm)

View B



Dimensions without specified tolerances ±1 mm.

- ① Check motor shaft fit.
- ② Min./max. permissible motor shaft length. Longer motor shaft is possible. Please call alpha.
- ③ The dimensions depend on the motor.
- ④ Smaller motor shaft diameter is compensated by a bushing with at least 1 mm thickness (see page 34).

▲ Motor mounting according to operating manual.

Technical Specifications SP+ 060 1-stage

			1-stage					
Ratio *	i		3	4	5	7	10	
Maximum acceleration torque (max. 1000 cycles per hour)	T_{2B}	Nm	30	40	40	40	32	
Nominal output torque	T_{2N}	Nm	17	26	26	26	17	
Emergency stop torque (Permissible 1000 times during the lifespan of the gearhead)	T_{2Not}	Nm	80	100	100	100	80	
Nominal input speed (At 20 °C ambient temperature) **	n_{1N}	min ⁻¹	3300	3300	3300	4000	4000	
No-load running torque ($n_1=3000$ rpm) (At 20 °C gearhead temperature)	T_{012}	Nm	1.0	0.7	0.6	0.4	0.3	
Maximum input speed	n_{1Max}	min ⁻¹	6000	6000	6000	6000	6000	
Torsional backlash	j_t	arcmin	Standard ≤ 4 / Reduced ≤ 2					
Torsional rigidity	C_{t21}	Nm/arcmin	3.5					
Max. axial force ***	F_{2AMax}	N	2400					
Max. radial force ***	F_{2RMax}	N	2700					
Max. tilting moment	M_{2KMax}	Nm	152					
Efficiency at full load	η	%	97					
Service life (For calculation, see alpha Technical Basics catalog)	L_h	h	> 20 000					
Weight	m	kg	1.9					
Noise level ($n_1=3000$ rpm) ****	L_{PA}	dB(A)	≤ 64					
Max. permissible housing temperature		°C	+90					
Ambient temperature		°C	0 to +40					
Lubrication			Lubricated for lifetime					
Paint			Blue RAL 5002					
Direction of rotation			Motor and gearhead same direction					
Type of protection			IP 65					
Mass moment of inertia (referring to the drive)	J_1	kgcm ²	11	0.23	0.16	0.13	0.11	0.10
			14	0.31	0.24	0.22	0.19	0.18
Clamping hub diameter (mm)			19	0.74	0.67	0.64	0.62	0.61

* Binary ratios (8) available as an option. Consult alpha.

** For higher ambient temperature, reduce nominal input speed n_{1N} .

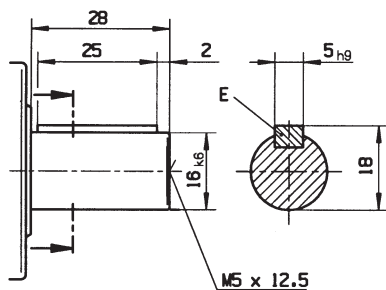
*** In reference to the center of the output shaft.

**** Measured at ratio $i = 5$ (without load).

Alternative output shaft versions

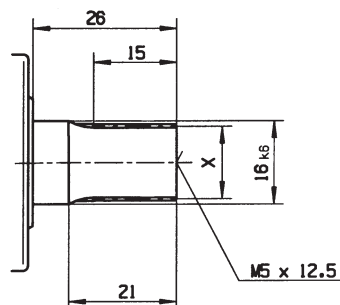
Keywayed output shaft in mm

E = Key to DIN 6885, page 1, form A



Involute gearing DIN 5480 in mm

X = W 16 x 0.8 x 30 x 18 x 6m, DIN 5480



Conversion table

1 mm	= 0.039 in
1 Nm	= 8.85 in.lb
1 kgcm ²	= 8.85×10^{-4} in.lb.s ²
1 N	= 0.225 lb _f
1 kg	= 2.21 lb _m

Technical Specifications **SP+ 060** 2-stage

			2-stage									
Ratio *	i		16	20	25	28	35	40	50	70	100	
Maximum acceleration torque (max. 1000 cycles per hour)	T_{2B}	Nm	40	40	40	40	40	40	40	40	32	
Nominal output torque	T_{2N}	Nm	26	26	26	26	26	26	26	26	17	
Emergency stop torque (Permissible 1000 times during the lifespan of the gearhead)	T_{2Not}	Nm	100	100	100	100	100	100	100	100	80	
Nominal input speed (At 20 °C ambient temperature) **	n_{1N}	min ⁻¹	4400	4400	4400	4400	4400	4400	4800	5500	5500	
No-load running torque ($n_1=3000$ rpm) (At 20 °C gearhead temperature)	T_{012}	Nm	0.3	0.3	0.3	0.3	0.3	0.3	0.2	0.2	0.2	
Maximum input speed	n_{1Max}	min ⁻¹	6000	6000	6000	6000	6000	6000	6000	6000	6000	
Torsional backlash	j_t	arcmin	Standard ≤ 6 / Reduced ≤ 4									
Torsional rigidity	C_{t21}	Nm/arcmin	3.5									
Max. axial force ***	F_{2AMax}	N	2400									
Max. radial force ***	F_{2RMMax}	N	2700									
Max. tilting moment	M_{2KMMax}	Nm	152									
Efficiency at full load	η	%	94									
Service life (For calculation, see alpha Technical Basics catalog)	L_h	h	> 20 000									
Weight	m	kg	2.0									
Noise level ($n_1=3000$ rpm) ****	L_{PA}	dB(A)	≤ 64									
Max. permissible housing temperature		°C	+90									
Ambient temperature		°C	0 to +40									
Lubrication			Lubricated for lifetime									
Paint			Blue RAL 5002									
Direction of rotation			Motor and gearhead same direction									
Type of protection			IP 65									
Mass moment of inertia (referring to the drive)	J_1	kgcm ²	11	0.08	0.07	0.07	0.06	0.06	0.06	0.06	0.06	0.06
Clamping hub diameter (mm)			14	0.18	0.17	0.17	0.16	0.16	0.16	0.16	0.16	0.16

* Binary ratios (32, 64) available as an option. Consult alpha.

** For higher ambient temperature, reduce nominal input speed n_{1N} .

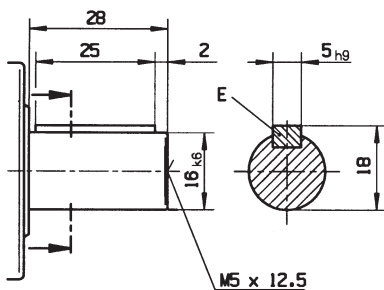
*** In reference to the center of the output shaft.

**** Measured at ratio $i = 5$ (without load).

Alternative output shaft versions

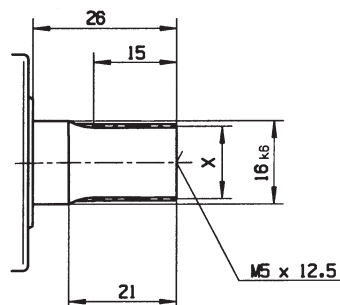
Keywayed output shaft in mm

E = Key to DIN 6885, page 1, form A



Involute gearing DIN 5480 in mm

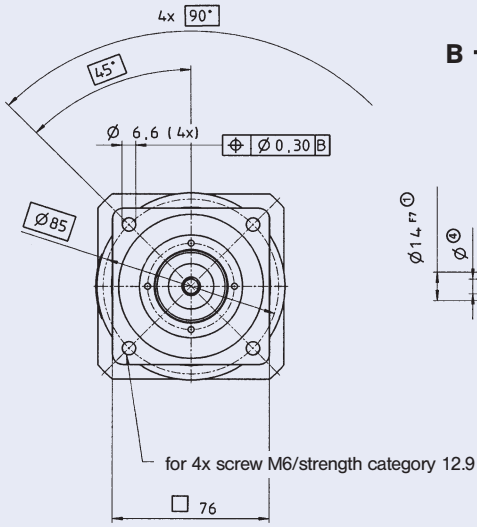
X = W 16 x 0.8 x 30 x 18 x 6m, DIN 5480



Conversion table

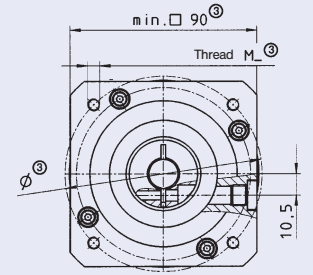
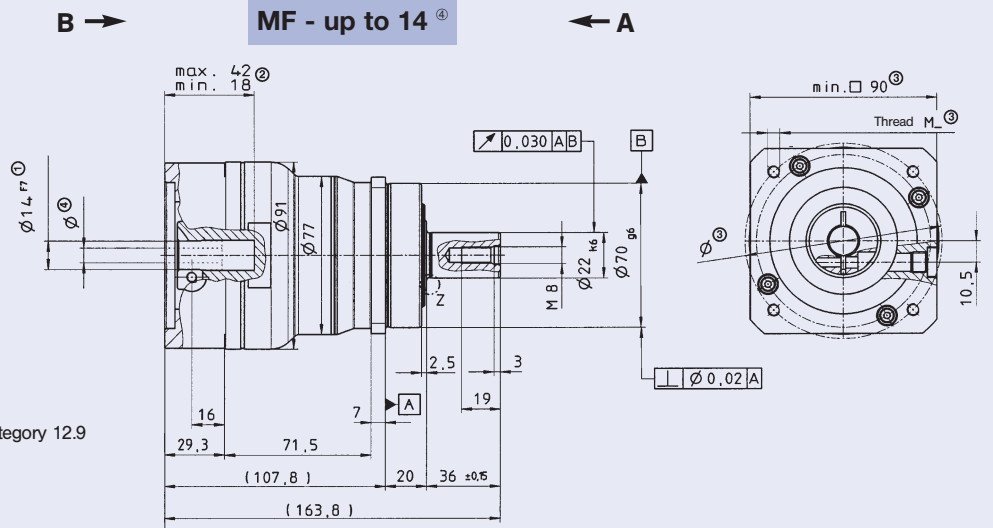
1 mm	= 0.039 in
1 Nm	= 8.85 in.lb
1 kgcm ²	= 8.85 x 10 ⁻⁴ in.lb.s ²
1 N	= 0.225 lb _f
1 kg	= 2.21 lb _m

View A



Motor shaft diameter (mm)

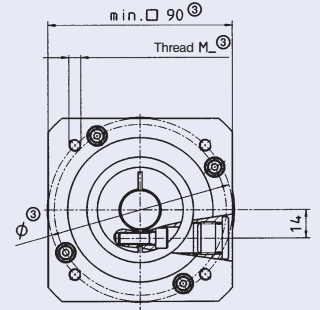
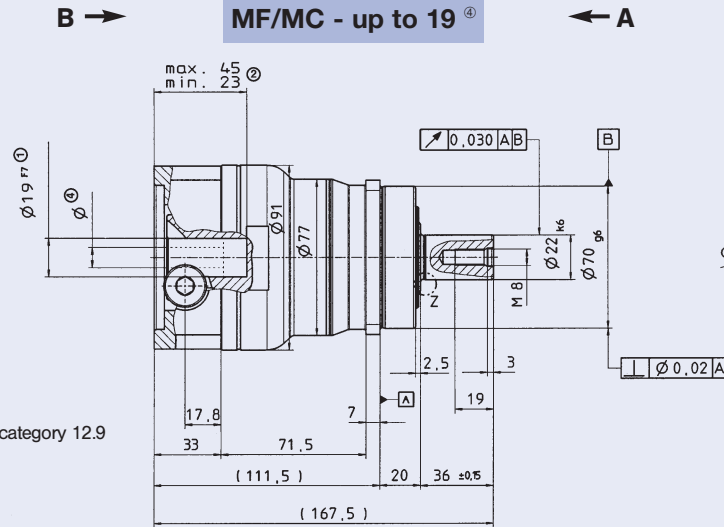
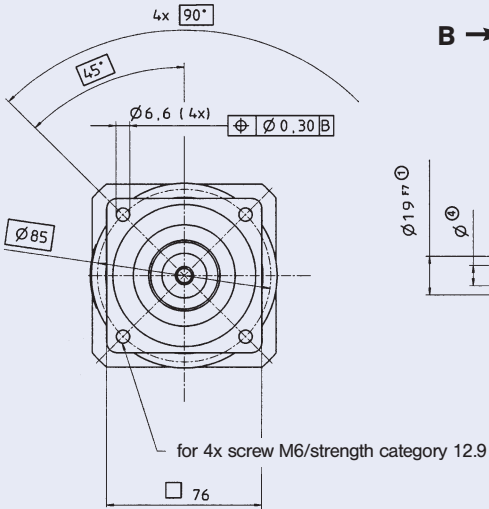
View B



B →

MF/MC - up to 19^④

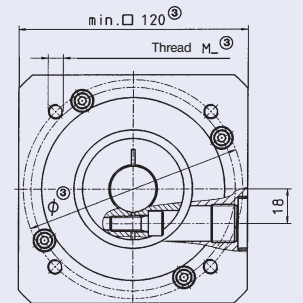
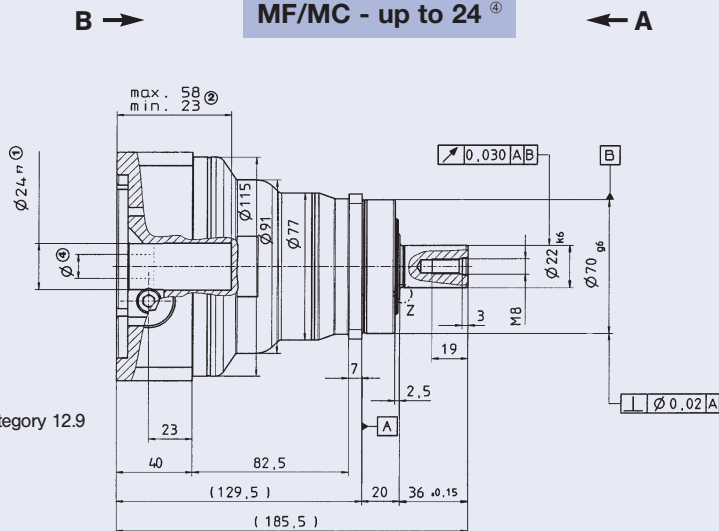
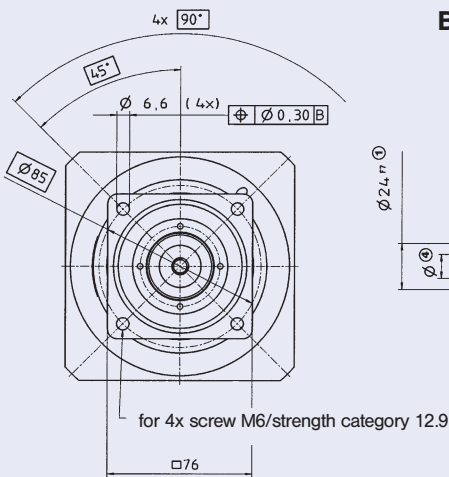
← A



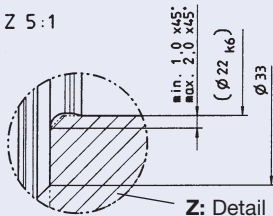
B →

MF/MC - up to 24^④

← A



Z 5:1



Z: Detail

Dimensions without specified tolerances ±1 mm.

① Check motor shaft fit.

② Min./max. permissible motor shaft length. Longer motor shaft is possible. Please call alpha.

③ The dimensions depend on the motor.

④ Smaller motor shaft diameter is compensated by a bushing with at least 1 mm thickness (see page 34).

⚠ Motor mounting according to operating manual.

MF = Cyclic operation S5
MC = Continuous operation S1

Technical Specifications SP+ 075 1-stage

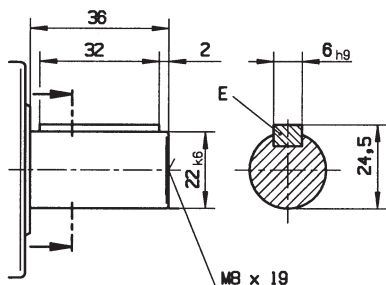
			1-stage					
Ratio *	i		3	4	5	7	10	
Maximum acceleration torque (max. 1000 cycles per hour)	T_{2B}	Nm	MF	85	110	110	110	90
			MC	42	61	66	66	42
Nominal output torque	T_{2N}	Nm	MF	47	75	75	75	52
			MC	26	39	41	42	26
Emergency stop torque (Permissible 1000 times during the lifespan of the gearhead)	T_{2Not}	Nm	200	250	250	250	200	
Nominal input speed (At 20 °C ambient temperature) **	n_{1N}	min ⁻¹	MF	2900	2900	2900	3100	3100
			MC	4500	4500	4500	4500	4500
No-load running torque ($n_1=3000$ rpm) (At 20 °C gearhead temperature)	T_{012}	Nm	MF	1.5	1.2	1.0	0.8	0.6
			MC	0.25	0.25	0.25	0.15	0.15
Maximum input speed	n_{1Max}	min ⁻¹	6000	6000	6000	6000	6000	
Torsional backlash	j_t	arcmin	MF	Standard ≤ 4 / Reduced ≤ 2				
			MC	Standard ≤ 6 / Reduced ≤ 4				
Torsional rigidity	C_{t21}	Nm/arcmin	10					
Max. axial force ***	F_{2AMax}	N	3350					
Max. radial force ***	F_{2RMax}	N	4000					
Max. tilting moment	M_{2KMax}	Nm	236					
Efficiency at full load	η	%	MF	97				
			MC	98.5				
Service life (For calculation, see alpha Technical Basics catalog)	L_h	h	MF	> 20 000				
			MC	> 30 000				
Weight	m	kg	3.9					
Noise level ($n_1=3000$ rpm) ****	L_{PA}	dB(A)	≤ 64					
Max. permissible housing temperature		°C	+90					
Ambient temperature		°C	0 to +40					
Lubrication			Lubricated for lifetime					
Paint			Blue RAL 5002					
Direction of rotation			Motor and gearhead same direction					
Type of protection			IP 65					
Mass moment of inertia (referring to the drive)	J_1	kgcm ²	14	0.94	0.69	0.58	0.48	0.42
			19	1.19	0.94	0.83	0.73	0.67
			24	2.81	2.56	2.45	2.35	2.30
Clamping hub diameter (mm)								

* Binary ratios (8) available as an option. Consult alpha.
 ** For higher ambient temperature, reduce nominal input speed n_{1N} .
 *** In reference to the center of the output shaft.
 **** Measured at ratio $i = 5$ (without load).

Alternative output shaft versions

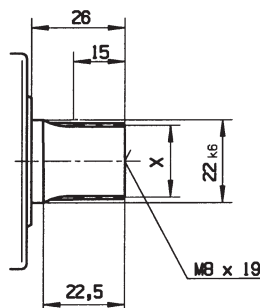
Keywayed output shaft in mm

E = Key to DIN 6885, page 1, form A



Involute gearing DIN 5480 in mm

X = W 22 x 1.25 x 30 x 16 x 6m, DIN 5480



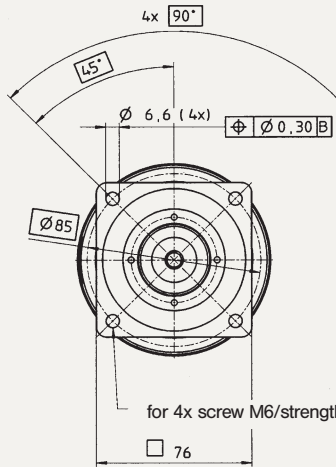
Conversion table

1 mm	= 0.039 in
1 Nm	= 8.85 in.lb
1 kgcm ²	= 8.85 x 10 ⁻⁴ in.lb.s ²
1 N	= 0.225 lb _f
1 kg	= 2.21 lb _m

View A

Motor shaft diameter (mm)

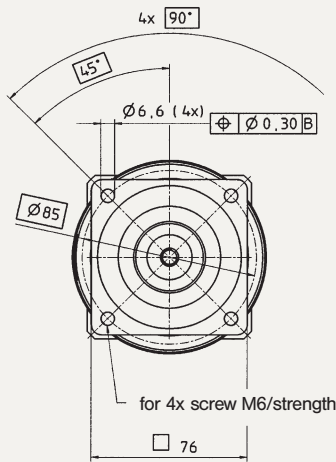
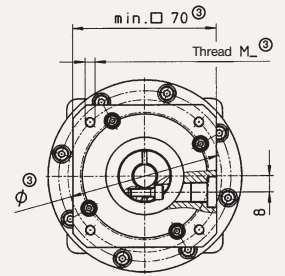
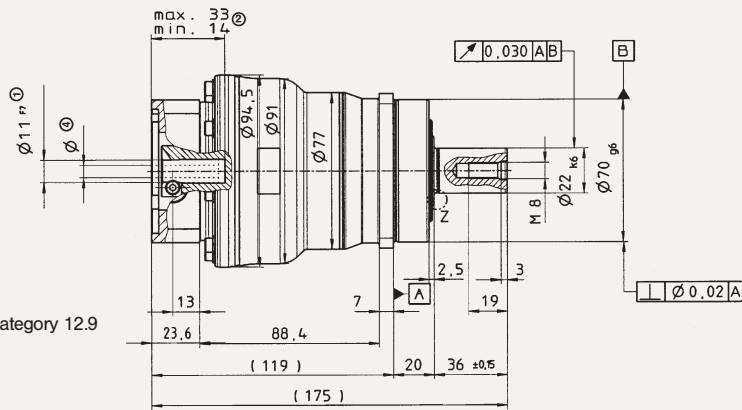
View B



B →

MF - up to 11^④

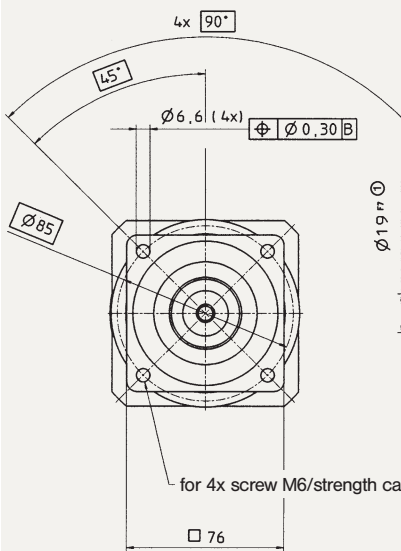
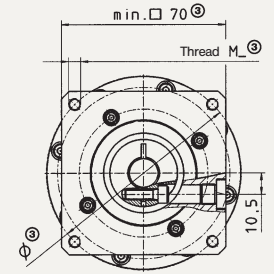
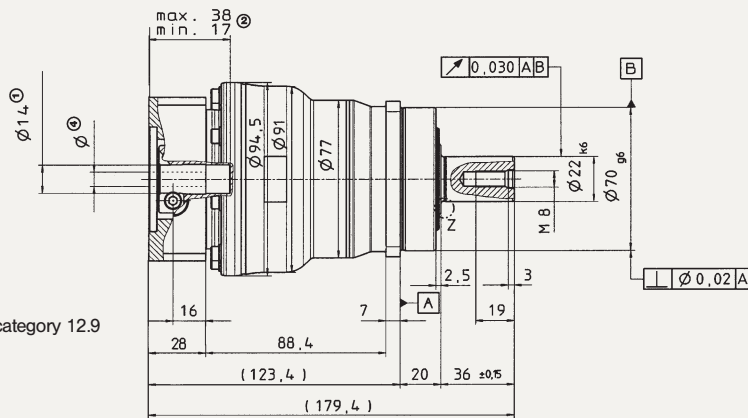
← A



B →

MF/MC - up to 14^④

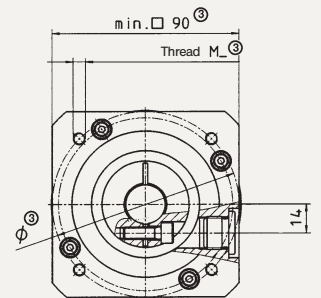
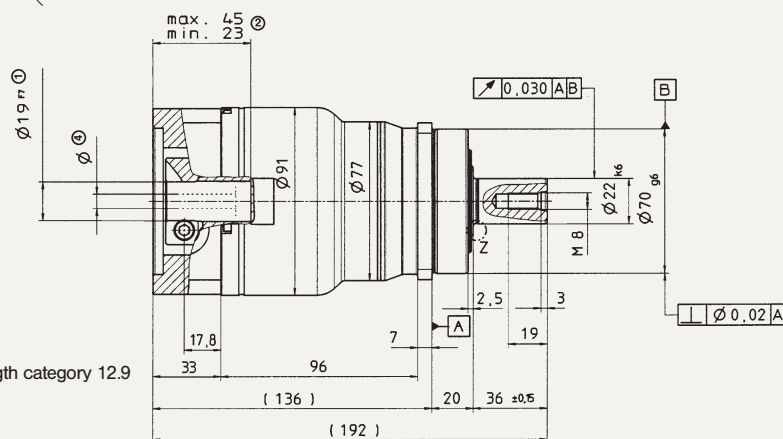
← A



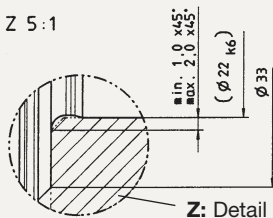
B →

MF/MC - up to 19^④

← A



Z 5:1



Dimensions without specified tolerances ±1 mm.

① Check motor shaft fit.

② Min./max. permissible motor shaft length. Longer motor shaft is possible. Please call alpha.

③ The dimensions depend on the motor.

④ Smaller motor shaft diameter is compensated by a bushing with at least 1 mm thickness (see page 34).

▲ Motor mounting according to operating manual.

MF = Cyclic operation S5
MC = Continuous operation S1

Technical Specifications **SP⁺ 075** 2-stage

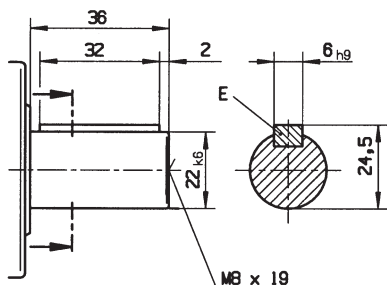
			2-stage									
Ratio *	i		16	20	25	28	35	40	50	70	100	
Maximum acceleration torque (max. 1000 cycles per hour)	T_{2B}	Nm	MF	110	110	110	110	110	110	110	110	90
			MC	61	66	66	66	66	61	66	66	42
Nominal output torque	T_{2N}	Nm	MF	75	75	75	75	75	75	75	75	52
			MC	39	41	41	42	41	39	41	42	26
Emergency stop torque (Permissible 1000 times during the lifespan of the gearhead)	T_{2Not}	Nm		250	250	250	250	250	250	250	200	
Nominal input speed (At 20 °C ambient temperature) **	n_{1N}	min ⁻¹	MF	3500	3500	3500	3500	3500	3500	3800	4500	4500
			MC	4500	4500	4500	4500	4500	4500	4500	4500	4500
No-load running torque ($n_1=3000$ rpm) (At 20 °C gearhead temperature)	T_{012}	Nm	MF	0.4	0.3	0.3	0.3	0.2	0.2	0.2	0.1	0.1
			MC	0.1	0.1	0.1	0.1	0.1	0.1	0.1	0.1	0.1
Maximum input speed	n_{1Max}	min ⁻¹		6000	6000	6000	6000	6000	6000	6000	6000	
Torsional backlash	j_t	arcmin	MF	Standard ≤ 6 / Reduced ≤ 4								
			MC	Standard ≤ 8 / Reduced ≤ 6								
Torsional rigidity	C_{t21}	Nm/arcmin		10								
Max. axial force ***	F_{2AMax}	N		3350								
Max. radial force ***	F_{2RMMax}	N		4000								
Max. tilting moment	M_{2KMMax}	Nm		236								
Efficiency at full load	η	%	MF	94								
			MC	96.5								
Service life (For calculation, see alpha Technical Basics catalog)	L_h	h	MF	> 20 000								
			MC	> 30 000								
Weight	m	kg		3.6								
Noise level ($n_1=3000$ rpm) ****	L_{PA}	dB(A)		≤ 64								
Max. permissible housing temperature		°C		+90								
Ambient temperature		°C		0 to +40								
Lubrication				Lubricated for lifetime								
Paint				Blue RAL 5002								
Direction of rotation				Motor and gearhead same direction								
Type of protection				IP 65								
Mass moment of inertia (referring to the drive)	J_1	kgcm ²	11	0.17	0.14	0.14	0.11	0.11	0.10	0.10	0.10	0.10
			14	0.25	0.22	0.22	0.19	0.19	0.18	0.18	0.18	0.18
			19	0.68	0.65	0.64	0.62	0.62	0.61	0.61	0.60	0.60
Clamping hub diameter (mm)												

- * Binary ratios (32, 64) available as an option. Consult alpha.
 ** For higher ambient temperature, reduce nominal input speed n_{1N} .
 *** In reference to the center of the output shaft.
 **** Measured at ratio $i = 5$ (without load).

Alternative output shaft versions

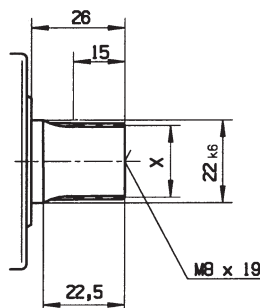
Keywayed output shaft in mm

E = Key to DIN 6885, page 1, form A



Involute gearing DIN 5480 in mm

X = W 22 x 1.25 x 30 x 16 x 6m, DIN 5480



Conversion table

1 mm	= 0.039 in
1 Nm	= 8.85 in.lb
1 kgcm ²	= 8.85 x 10 ⁻⁴ in.lb.s ²
1 N	= 0.225 lb _f
1 kg	= 2.21 lb _m



MF = Cyclic operation S5
MC = Continuous operation S1

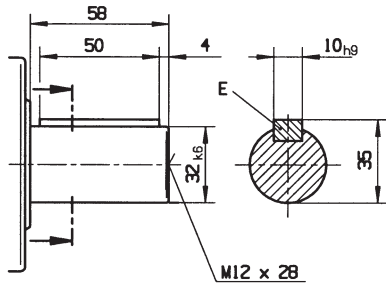
Technical Specifications SP+ 100 1-stage

			1-stage					
Ratio *	i		3	4	5	7	10	
Maximum acceleration torque (max. 1000 cycles per hour)	T_{2B}	Nm	MF	225	300	300	300	225
			MC	100	150	160	165	105
Nominal output torque	T_{2N}	Nm	MF	120	180	175	170	120
			MC	65	100	105	105	65
Emergency stop torque (Permissible 1000 times during the lifespan of the gearhead)	T_{2Not}	Nm	500	625	625	625	500	
Nominal input speed (At 20 °C ambient temperature) **	n_{1N}	min ⁻¹	MF	2500	2500	2500	2800	2800
			MC	3500	4000	4500	4500	4500
No-load running torque ($n_1=3000$ rpm) (At 20 °C gearhead temperature)	T_{012}	Nm	MF	3.2	2.7	2.3	1.9	1.3
			MC	0.5	0.5	0.5	0.4	0.4
Maximum input speed	n_{1Max}	min ⁻¹	MF	4500	4500	4500	4500	4500
			MC	6000	6000	6000	6000	6000
Torsional backlash	j_t	arcmin	MF	Standard ≤ 3 / Reduced ≤ 1				
			MC	Standard ≤ 4 / Reduced ≤ 2				
Torsional rigidity	C_{t21}	Nm/arcmin	31					
Max. axial force ***	F_{2AMax}	N	5650					
Max. radial force ***	F_{2RMMax}	N	6300					
Max. tilting moment	M_{2KMMax}	Nm	487					
Efficiency at full load	η	%	MF	97				
			MC	98.5				
Service life (For calculation, see alpha Technical Basics catalog)	L_h	h	MF	> 20 000				
			MC	> 30 000				
Weight	m	kg	7.7					
Noise level ($n_1=3000$ rpm) ****	L_{PA}	dB(A)	≤ 66					
Max. permissible housing temperature		°C	+90					
Ambient temperature		°C	0 to +40					
Lubrication			Lubricated for lifetime					
Paint			Blue RAL 5002					
Direction of rotation			Motor and gearhead same direction					
Type of protection			IP 65					
Mass moment of inertia J_1 (referring to the drive)		kgcm ²	19	3.65	2.62	2.14	1.78	1.55
			24	4.68	3.65	2.99	2.81	2.58
			28	4.57	3.54	2.88	2.70	2.47
			38	10.46	9.43	8.95	8.59	8.36
Clamping hub diameter (mm)								

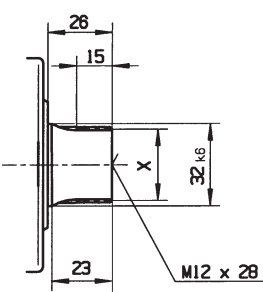
* Binary ratios (8) available as an option. Consult alpha.
 ** For higher ambient temperature, reduce nominal input speed n_{1N} .
 *** In reference to the center of the output shaft.
 **** Measured at ratio $i = 5$ (without load).

Alternative output shaft versions

Keywayed output shaft in mm
 E = Key to DIN 6885, page 1, form A



Involute gearing DIN 5480 in mm
 X = W 32 x 1.25 x 30 x 24 x 6m, DIN 5480



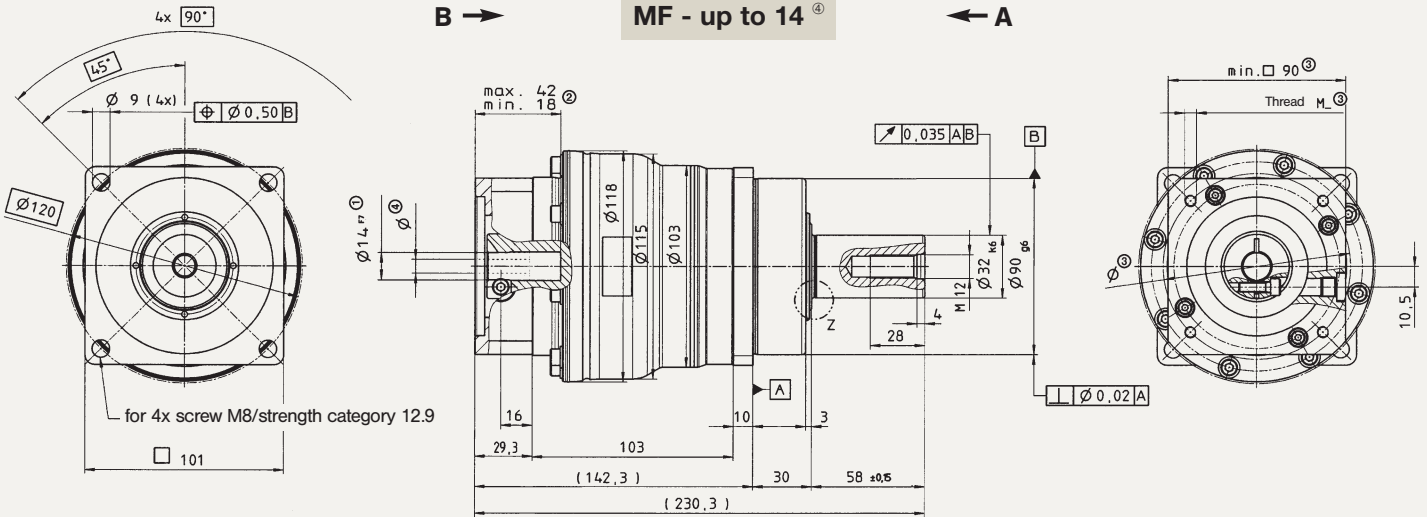
1 mm	= 0.039 in
1 Nm	= 8.85 in.lb
1 kgcm ²	= 8.85 x 10 ⁻⁴ in.lb.s ²
1 N	= 0.225 lb _f
1 kg	= 2.21 lb _m

View A

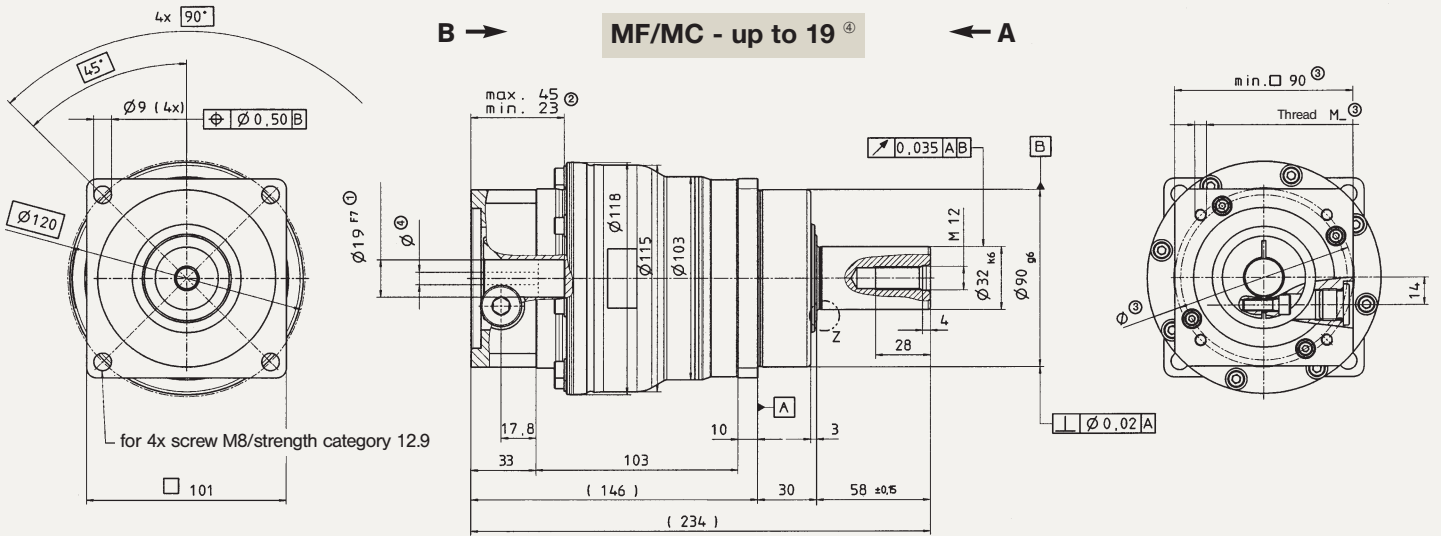
Motor shaft diameter (mm)

View B

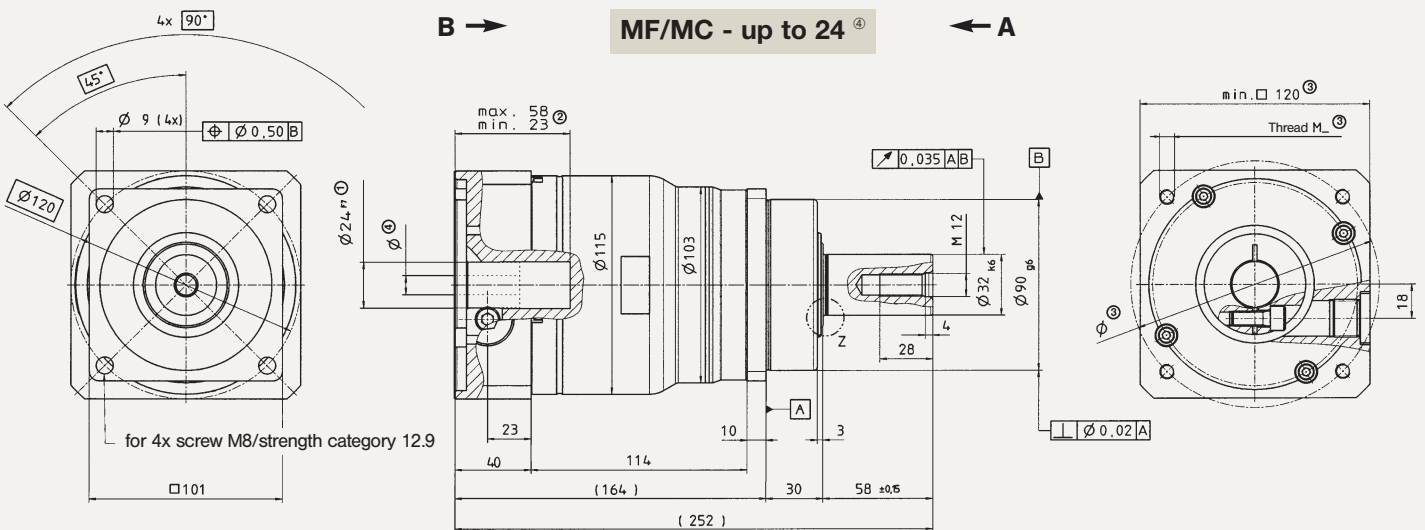
MF - up to 14^④



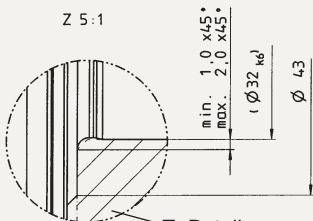
MF/MC - up to 19^④



MF/MC - up to 24^④



Z 5:1



Z: Detail

Dimensions without specified tolerances ± 1 mm.

① Check motor shaft fit.

② Min./max. permissible motor shaft length. Longer motor shaft is possible. Please call alpha.

③ The dimensions depend on the motor.

④ Smaller motor shaft diameter is compensated by a bushing with at least 1 mm thickness (see page 34).

⚠ Motor mounting according to operating manual.

MF = Cyclic operation S5
MC = Continuous operation S1

Technical Specifications **SP+ 100** 2-stage

				2-stage									
Ratio *	i			16	20	25	28	35	40	50	70	100	
Maximum acceleration torque (max. 1000 cycles per hour)	T_{2B}	Nm	MF	300	300	300	300	300	300	300	300	225	
			MC	150	160	160	165	160	150	160	165	105	
Nominal output torque	T_{2N}	Nm	MF	180	180	175	180	175	180	175	170	120	
			MC	100	105	105	105	105	100	105	105	65	
Emergency stop torque (Permissible 1000 times during the lifespan of the gearhead)	T_{2Not}	Nm		625	625	625	625	625	625	625	625	500	
Nominal input speed (At 20 °C ambient temperature) **	n_{1N}	min ⁻¹	MF	3100	3100	3100	3100	3100	3100	3500	4200	4200	
			MC	4500	4500	4500	4500	4500	4500	4500	4500	4500	
No-load running torque ($n_1=3000$ rpm) (At 20 °C gearhead temperature)	T_{012}	Nm	MF	1.1	1.0	0.9	0.8	0.7	0.6	0.6	0.5	0.4	
			MC	0.3	0.3	0.3	0.3	0.3	0.3	0.3	0.3	0.3	
Maximum input speed	n_{1Max}	min ⁻¹	MF	4500	4500	4500	4500	4500	4500	4500	4500	4500	
			MC	6000	6000	6000	6000	6000	6000	6000	6000	6000	
Torsional backlash	j_t	arcmin	MF	Standard ≤ 5 / Reduced ≤ 3									
			MC	Standard ≤ 6 / Reduced ≤ 4									
Torsional rigidity	C_{t21}	Nm/arcmin		31									
Max. axial force ***	F_{2AMax}	N		5650									
Max. radial force ***	F_{2RMax}	N		6300									
Max. tilting moment	M_{2KMMax}	Nm		487									
Efficiency at full load	η	%	MF	94									
			MC	96.5									
Service life (For calculation, see alpha Technical Basics catalog)	L_h	h	MF	> 20 000									
			MC	> 30 000									
Weight	m	kg		7.9									
Noise level ($n_1=3000$ rpm) ****	L_{PA}	dB(A)		≤ 66									
Max. permissible housing temperature		°C		+90									
Ambient temperature		°C		0 to +40									
Lubrication				Lubricated for lifetime									
Paint				Blue RAL 5002									
Direction of rotation				Motor and gearhead same direction									
Type of protection				IP 65									
Mass moment of inertia (referring to the drive)	J_1	kgcm ²	14	0.72	0.6	0.58	0.49	0.48	0.43	0.43	0.42	0.42	
			19	0.96	0.84	0.82	0.73	0.72	0.67	0.66	0.66	0.66	
			24	2.6	2.48	2.46	2.36	2.35	2.31	2.3	2.3	2.29	
Clamping hub diameter (mm)													

* Binary ratios (32, 64) available as an option. Consult alpha.

** For higher ambient temperature, reduce nominal input speed n_{1N} .

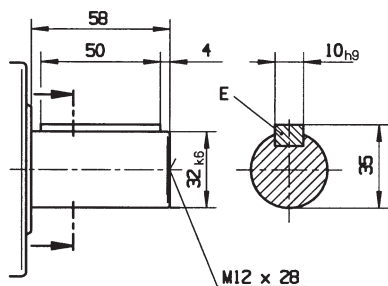
*** In reference to the center of the output shaft.

**** Measured at ratio $i = 5$ (without load).

Alternative output shaft versions

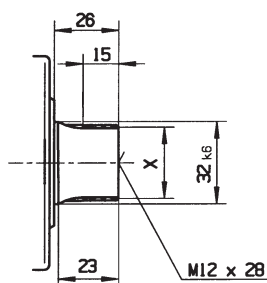
Keywayed output shaft in mm

E = Key to DIN 6885, page 1, form A



Involute gearing DIN 5480 in mm

X = W 32 x 1.25 x 30 x 24 x 6m, DIN 5480



Conversion table

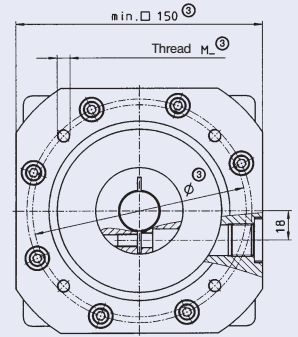
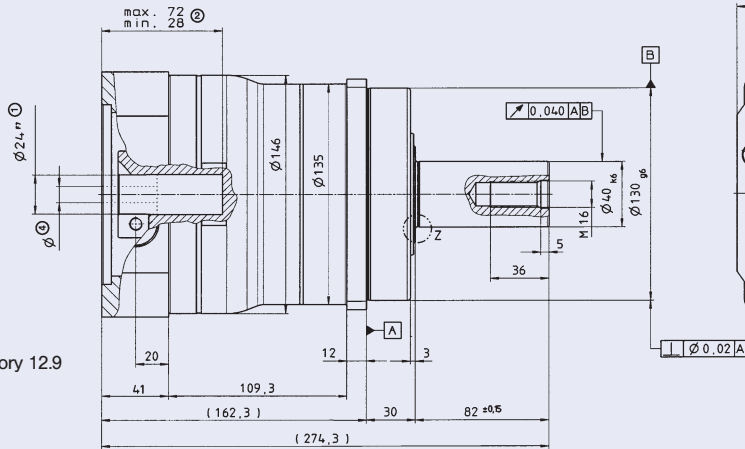
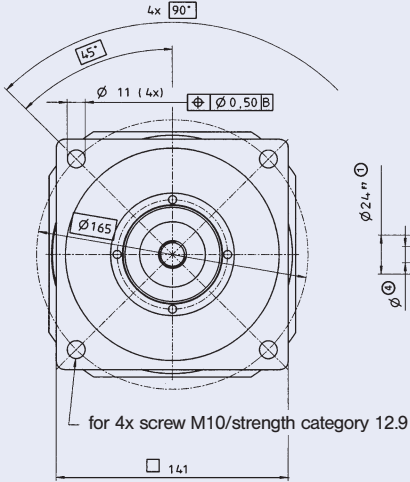
1 mm	= 0.039 in
1 Nm	= 8.85 in.lb
1 kgcm ²	= 8.85 x 10 ⁻⁴ in.lb.s ²
1 N	= 0.225 lb _f
1 kg	= 2.21 lb _m

View A

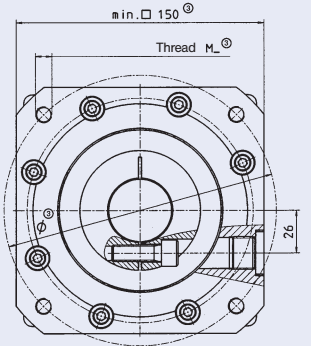
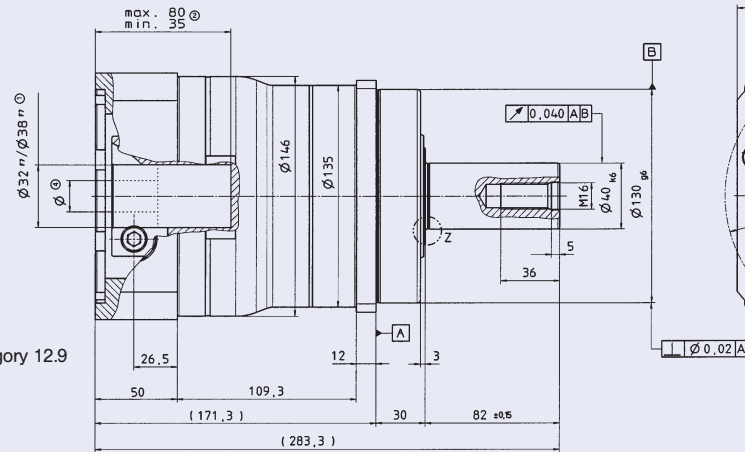
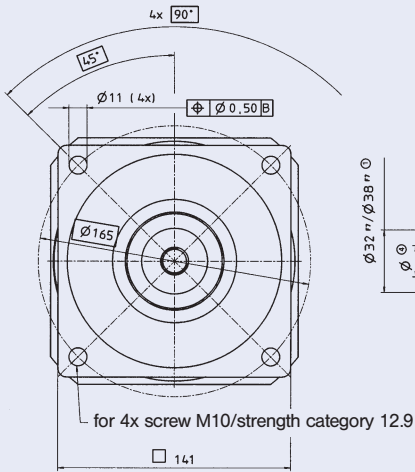
Motor shaft diameter (mm)

View B

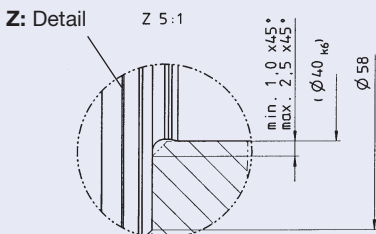
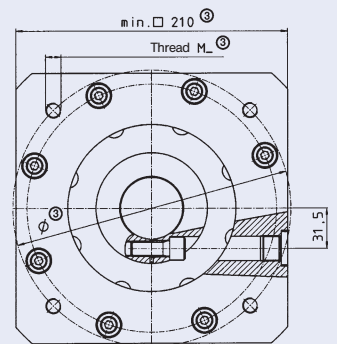
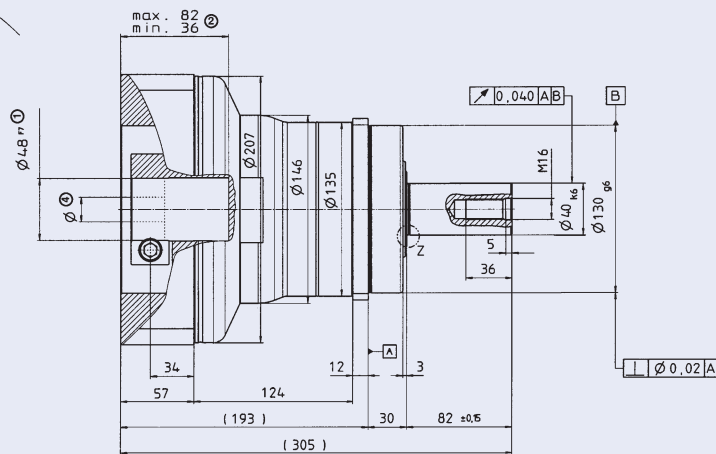
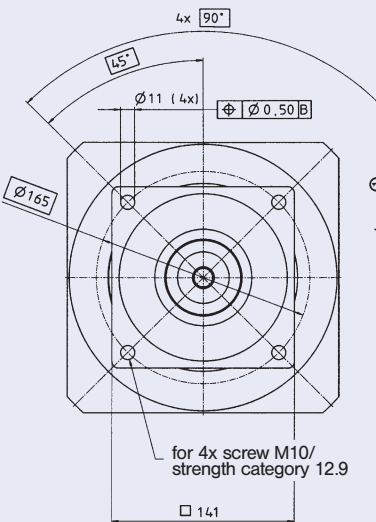
MF - up to 24^④



MF - up to 32/38^④
MC - up to 38^④



MF - up to 48^④



Dimensions without specified tolerances ±1 mm.

- ① Check motor shaft fit.
- ② Min./max. permissible motor shaft length. Longer motor shaft is possible. Please call alpha.
- ③ The dimensions depend on the motor.
- ④ Smaller motor shaft diameter is compensated by a bushing with at least 1 mm thickness (see page 34).

⚠ Motor mounting according to operating manual.

MF = Cyclic operation S5
MC = Continuous operation S1

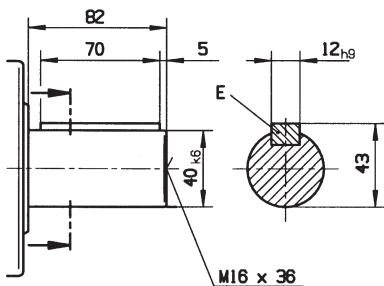
Technical Specifications SP+ 140 1-stage

			1-stage					
Ratio *	i		3	4	5	7	10	
Maximum acceleration torque (max. 1000 cycles per hour)	T_{2B}	Nm	MF	390	600	600	600	480
			MC	200	230	320	330	195
Nominal output torque	T_{2N}	Nm	MF	200	360	360	360	220
			MC	130	195	205	210	120
Emergency stop torque (Permissible 1000 times during the lifespan of the gearhead)	T_{2Not}	Nm	1000	1250	1250	1250	1000	
Nominal input speed (At 20 °C ambient temperature) **	n_{1N}	min ⁻¹	MF	2100	2100	2100	2600	2600
			MC	3000	3500	4500	4500	4500
No-load running torque ($n_1=3000$ rpm) (At 20 °C gearhead temperature)	T_{012}	Nm	MF	6.5	4.5	3.8	3.2	2.3
			MC	0.75	0.75	0.75	0.55	0.55
Maximum input speed	n_{1Max}	min ⁻¹	MF	4000	4000	4000	4000	4000
			MC	6000	6000	6000	6000	6000
Torsional backlash	j_t	arcmin	MF	Standard ≤ 3 / Reduced ≤ 1				
			MC	Standard ≤ 4 / Reduced ≤ 2				
Torsional rigidity	C_{t21}	Nm/arcmin	53					
Max. axial force ***	F_{2AMax}	N	9870					
Max. radial force ***	F_{2RMax}	N	9450					
Max. tilting moment	M_{2KMax}	Nm	952					
Efficiency at full load	η	%	MF	97				
			MC	98.5				
Service life (For calculation, see alpha Technical Basics catalog)	L_h	h	MF	> 20 000				
			MC	> 30 000				
Weight	m	kg	17.2					
Noise level ($n_1=3000$ rpm) ****	L_{PA}	dB(A)	≤ 66					
Max. permissible housing temperature		°C	+90					
Ambient temperature		°C	0 to +40					
Lubrication			Lubricated for lifetime					
Paint			Blue RAL 5002					
Direction of rotation			Motor and gearhead same direction					
Type of protection			IP 65					
Mass moment of inertia (referring to the drive)	J_1	kgcm ²	24	12.3	8.66	7.46	6.38	5.8
			32	17.89	14.26	13.06	11.97	11.39
			38	17.32	13.68	12.47	11.39	10.81
			48	28.48	24.84	23.64	22.55	21.97
Clamping hub diameter (mm)								

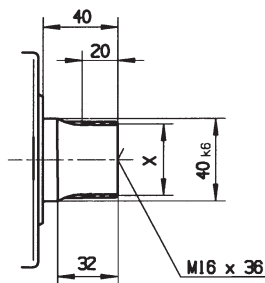
* Binary ratios (β) available as an option. Consult alpha.
 ** For higher ambient temperature, reduce nominal input speed n_{1N} .
 *** In reference to the center of the output shaft.
 **** Measured at ratio $i = 5$ (without load).

Alternative output shaft versions

Keywayed output shaft in mm
 E = Key to DIN 6885, page 1, form A



Involute gearing DIN 5480 in mm
 X = W 40 x 2 x 30 x 18 x 6m, DIN 5480



1 mm	= 0.039 in
1 Nm	= 8.85 in.lb
1 kgcm ²	= 8.85 x 10 ⁻⁴ in.lb.s ²
1 N	= 0.225 lb _f
1 kg	= 2.21 lb _m

MF = Cyclic operation S5
MC = Continuous operation S1

Technical Specifications **SP+ 140 2-stage**

			2-stufig									
Ratio *	i		16	20	25	28	35	40	50	70	100	
Maximum acceleration torque (max. 1000 cycles per hour)	T_{2B}	Nm	MF	600	600	600	600	600	600	600	600	480
			MC	230	320	320	330	320	230	320	330	195
Nominal output torque	T_{2N}	Nm	MF	360	360	360	360	360	360	360	360	220
			MC	195	205	205	210	205	195	205	210	120
Emergency stop torque (Permissible 1000 times during the lifespan of the gearhead)	T_{2Not}	Nm	1250	1250	1250	1250	1250	1250	1250	1250	1000	
Nominal input speed (At 20 °C ambient temperature) **	n_{1N}	min ⁻¹	MF	2900	2900	2900	2900	2900	2900	3200	3200	3900
			MC	4500	4500	4500	4500	4500	4500	4500	4500	4500
No-load running torque ($n_1=3000$ rpm) (At 20 °C gearhead temperature)	T_{012}	Nm	MF	1.6	1.6	1.5	1.5	1.4	1.4	1.3	1.2	1.1
			MC	0.4	0.4	0.4	0.4	0.4	0.4	0.4	0.4	0.4
Maximum input speed	n_{1Max}	min ⁻¹	MF	4000	4000	4000	4000	4000	4000	4000	4000	4000
			MC	6000	6000	6000	6000	6000	6000	6000	6000	6000
Torsional backlash	j_t	arcmin	MF	Standard ≤ 5 / Reduced ≤ 3								
			MC	Standard ≤ 6 / Reduced ≤ 4								
Torsional rigidity	C_{t21}	Nm/arcmin	53									
Max. axial force ***	F_{2AMax}	N	9870									
Max. radial force ***	F_{2RMMax}	N	9450									
Max. tilting moment	M_{2KMax}	Nm	952									
Efficiency at full load	η	%	MF	94								
			MC	96.5								
Service life (For calculation, see alpha Technical Basics catalog)	L_h	h	MF	$> 20\ 000$								
			MC	$> 30\ 000$								
Weight	m	kg	17									
Noise level ($n_1=3000$ rpm) ****	L_{PA}	dB(A)	≤ 66									
Max. permissible housing temperature		°C	$+90$									
Ambient temperature		°C	0 to $+40$									
Lubrication			Lubricated for lifetime									
Paint			Blue RAL 5002									
Direction of rotation			Motor and gearhead same direction									
Type of protection			IP 65									
Mass moment of inertia (referring to the drive)	J_1	kgcm ²	19	2.79	2.26	2.21	1.84	1.82	1.58	1.57	1.56	1.55
			24	3.61	3.08	3.08	2.66	2.63	2.39	2.38	2.37	2.37
			38	9.6	9.07	9.07	8.65	8.63	8.39	8.37	8.36	8.36
Clamping hub diameter (mm)												

* Binary ratios (32, 64) available as an option. Consult alpha.

** For higher ambient temperature, reduce nominal input speed n_{1N} .

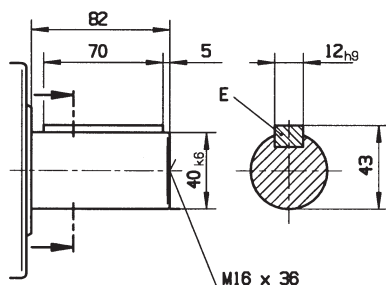
*** In reference to the center of the output shaft.

**** Measured at ratio $i = 5$ (without load).

Alternative output shaft versions

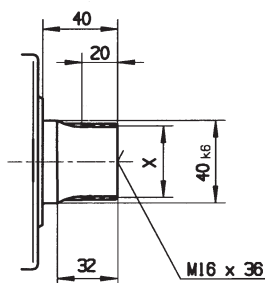
Keywayed output shaft in mm

E = Key to DIN 6885, page 1, form A



Involute gearing DIN 5480 in mm

X = W 40 x 2 x 30 x 18 x 6m, DIN 5480



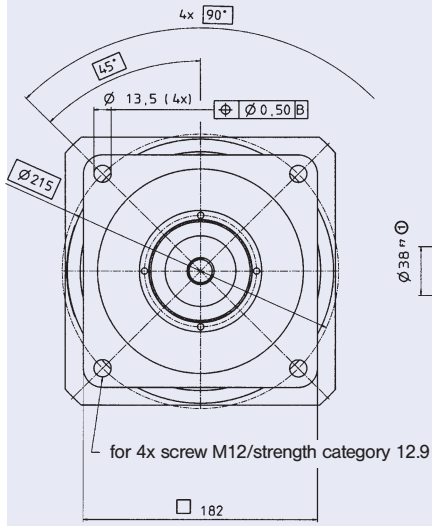
Conversion table

1 mm	= 0.039 in
1 Nm	= 8.85 in.lb
1 kgcm ²	= 8.85 x 10 ⁻⁴ in.lb.s ²
1 N	= 0.225 lb _f
1 kg	= 2.21 lb _m

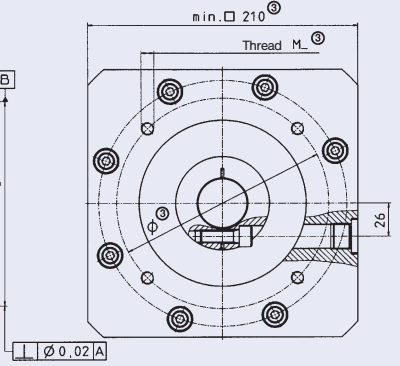
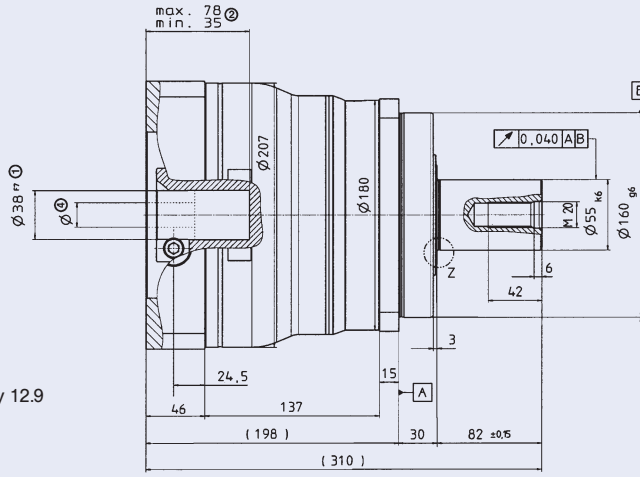
View A

Motor shaft diameter (mm)

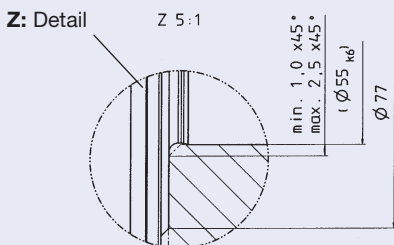
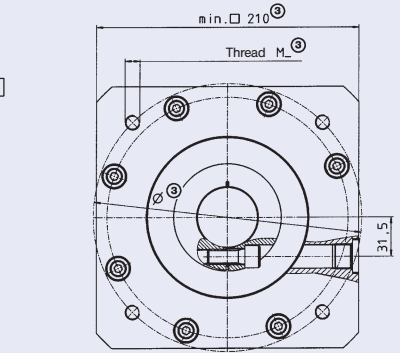
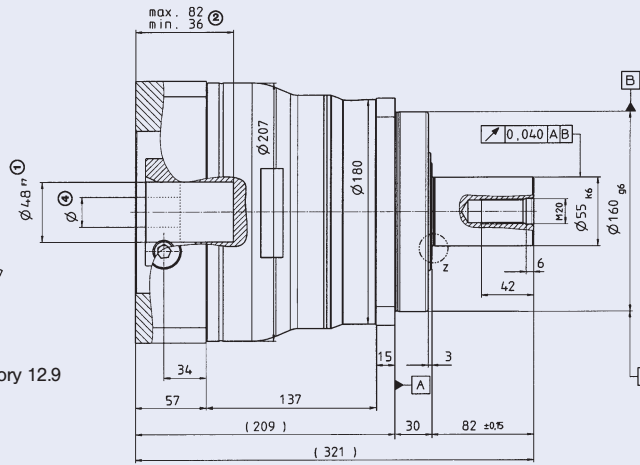
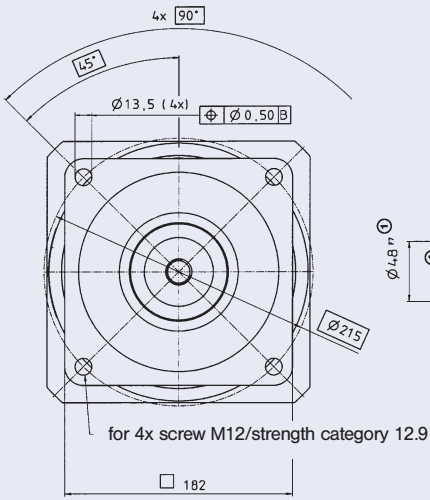
View B



B → MF - up to 38^④ ← A



B → MF/MC - up to 48^④ ← A



Dimensions without specified tolerances ±1 mm.

① Check motor shaft fit.

② Min./max. permissible motor shaft length. Longer motor shaft is possible. Please call alpha.

③ The dimensions depend on the motor.

④ Smaller motor shaft diameter is compensated by a bushing with at least 1 mm thickness (see page 34).

⚠ Motor mounting according to operating manual.

MF = Cyclic operation S5
MC = Continuous operation S1

Technical Specifications SP+ 180 1-stage

				1-stage				
Ratio *	i			3	4	5	7	10
Maximum acceleration torque (max. 1000 cycles per hour)	T_{2B}	Nm	MF	880	1100	1100	1100	880
			MC	275	410	430	450	485
Nominal output torque	T_{2N}	Nm	MF	530	750	750	750	750
			MC	170	255	270	275	305
Emergency stop torque (Permissible 1000 times during the lifespan of the gearhead)	T_{2Not}	Nm		2200	2750	2750	2750	2200
Nominal input speed (At 20 °C ambient temperature) **	n_{1N}	min ⁻¹	MF	1500	1500	1500	2300	2300
			MC	3000	3500	4500	4500	4500
No-load running torque ($n_1=3000$ rpm) (At 20 °C gearhead temperature)	T_{012}	Nm	MF	11	9	7.2	5.1	2.3
			MC	1.0	1.0	1.0	0.75	0.75
Maximum input speed	n_{1Max}	min ⁻¹	MF	3500	3500	3500	3500	3500
			MC	4500	6000	6000	6000	6000
Torsional backlash	j_t	arcmin	MF	Standard ≤ 3 / Reduced ≤ 1				
			MC	Standard ≤ 4 / Reduced ≤ 2				
Torsional rigidity	C_{21}	Nm/arcmin		175				
Max. axial force ***	F_{2AMax}	N		14 150				
Max. radial force ***	F_{2RMax}	N		14 700				
Max. tilting moment	M_{2KMMax}	Nm		1600				
Efficiency at full load	η	%	MF	97				
			MC	98.5				
Service life (For calculation, see alpha Technical Basics catalog)	L_h	h	MF	> 20 000				
			MC	> 30 000				
Weight	m	kg		34				
Noise level ($n_1=3000$ rpm) ****	L_{PA}	dB(A)		≤ 66				
Max. permissible housing temperature		°C		+90				
Ambient temperature		°C		0 to +40				
Lubrication				Lubricated for lifetime				
Paint				Blue RAL 5002				
Direction of rotation				Motor and gearhead same direction				
Type of protection				IP 65				
Mass moment of inertia (referring to the drive)	J_1	kgcm ²	38	61.70	41.72	34.24	27.26	23.62
			48	63.57	43.79	36.90	30.18	26.67
Clamping hub diameter (mm)				63.57	43.79	36.90	30.18	26.67

* Binary ratios (8) available as an option. Consult alpha.

** For higher ambient temperature, reduce nominal input speed n_{1N} .

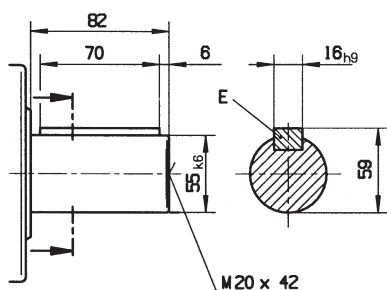
*** In reference to the center of the output shaft.

**** Measured at ratio $i = 5$ (without load).

Alternative output shaft versions

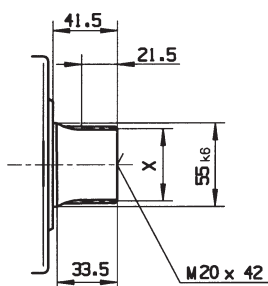
Keywayed output shaft in mm

E = Key to DIN 6885, page 1, form A



Involute gearing DIN 5480 in mm

X = W 55 x 2 x 30 x 26 x 6m, DIN 5480



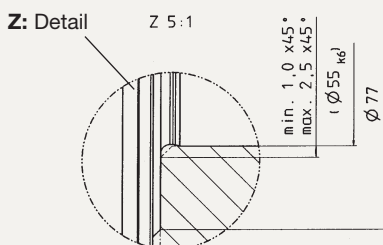
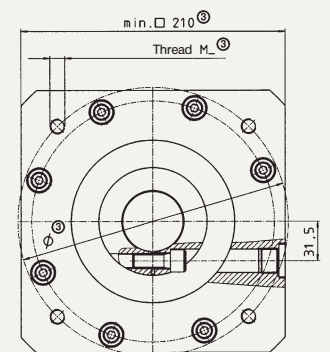
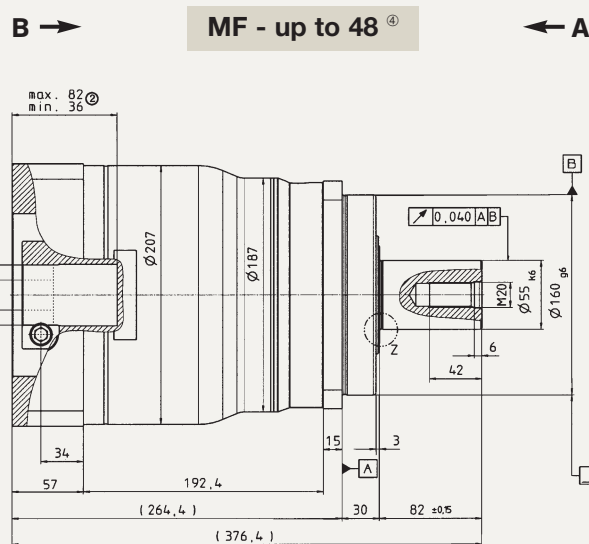
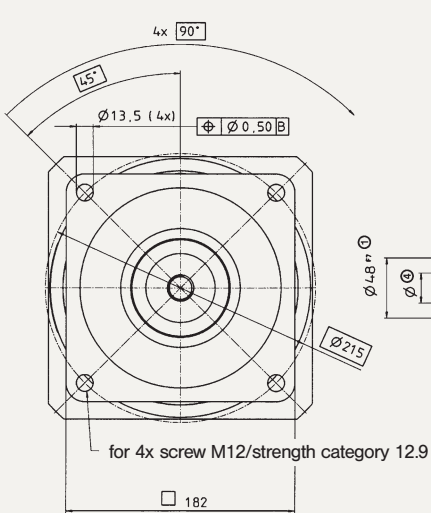
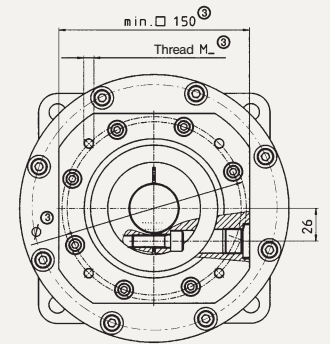
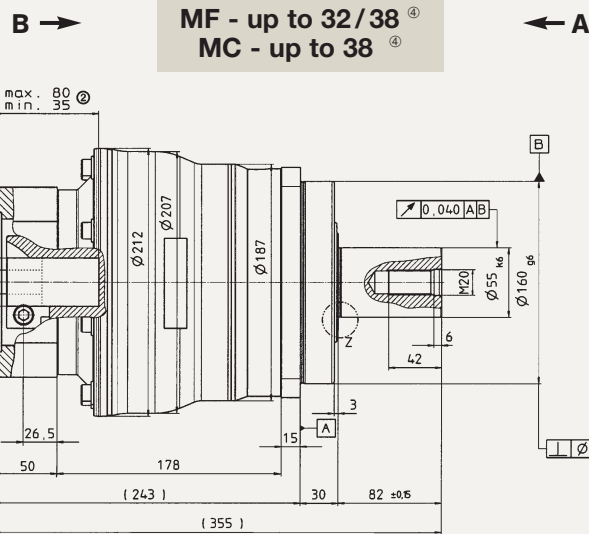
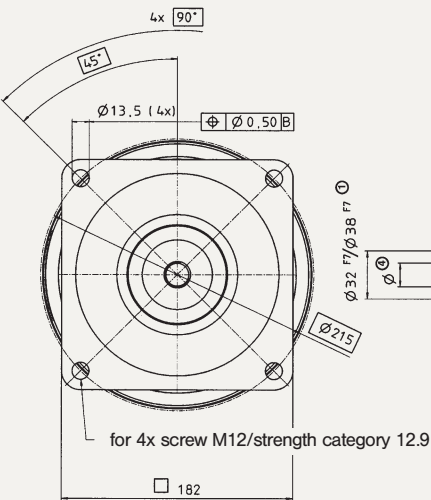
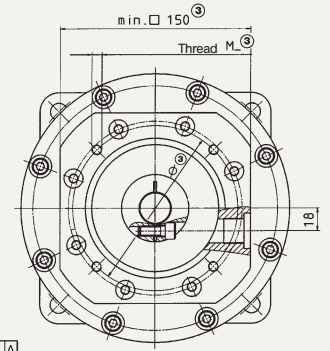
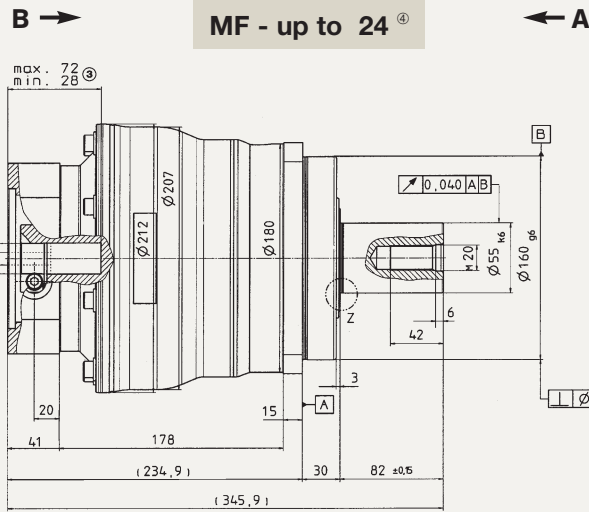
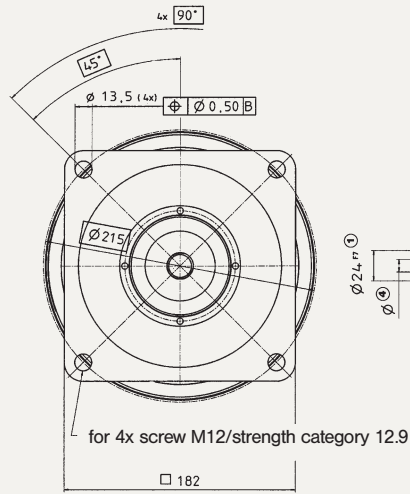
Conversion table

1 mm	= 0.039 in
1 Nm	= 8.85 in.lb
1 kgcm ²	= 8.85 x 10 ⁻⁴ in.lb.s ²
1 N	= 0.225 lb _f
1 kg	= 2.21 lb _m

View A

Motor shaft diameter (mm)

View B



Dimensions without specified tolerances ±1 mm.

① Check motor shaft fit.

② Min./max. permissible motor shaft length. Longer motor shaft is possible. Please call alpha.

③ The dimensions depend on the motor.

④ Smaller motor shaft diameter is compensated by a bushing with at least 1 mm thickness (see page 34).

⚠ Motor mounting according to operating manual.

MF = Cyclic operation S5
MC = Continuous operation S1

Technical Specifications SP+ 180 2-stage

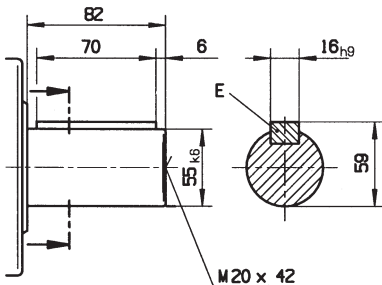
			2-stage									
Ratio *	i		16	20	25	28	35	40	50	70	100	
Maximum acceleration torque (max. 1000 cycles per hour)	T_{2B}	Nm	MF	1100	1100	1100	1100	1100	1100	1100	1100	880
			MC	410	430	430	450	430	410	430	450	485
Nominal output torque	T_{2N}	Nm	MF	750	750	750	750	750	750	750	750	750
			MC	255	270	270	275	270	255	270	275	305
Emergency stop torque (Permissible 1000 times during the lifespan of the gearhead)	T_{2Not}	Nm		2750	2750	2750	2750	2750	2750	2750	2750	2200
Nominal input speed (At 20 °C ambient temperature) **	n_{1N}	min ⁻¹	MF	2700	2700	2700	2700	2700	2700	2900	3200	3400
			MC	4500	4500	4500	4500	4500	4500	4500	4500	4500
No-load running torque ($n_1=3000$ rpm) (At 20 °C gearhead temperature)	T_{012}	Nm	MF	2.9	2.7	2.5	2.3	2.0	1.8	1.7	1.5	1.3
			MC	0.5	0.5	0.5	0.5	0.5	0.5	0.5	0.5	0.5
Maximum input speed	n_{1Max}	min ⁻¹	MF	4000	4000	4000	4000	4000	4000	4000	4000	4000
			MC	6000	6000	6000	6000	6000	6000	6000	6000	6000
Torsional backlash	j_t	arcmin	MF	Standard ≤ 5 / Reduced ≤ 3								
			MC	Standard ≤ 6 / Reduced ≤ 4								
Torsional rigidity	C_{t21}	Nm/arcmin	175									
Max. axial force ***	F_{2AMax}	N	14 150									
Max. radial force ***	F_{2RMax}	N	14 700									
Max. tilting moment	M_{2KMax}	Nm	1600									
Efficiency at full load	η	%	MF	94								
			MC	96.5								
Service life (For calculation, see alpha Technical Basics catalog)	L_h	h	MF	> 20 000								
			MC	> 30 000								
Weight	m	kg	36.4									
Noise level ($n_1=3000$ rpm) ****	L_{PA}	dB(A)	≤ 66									
Max. permissible housing temperature		°C	+90									
Ambient temperature		°C	0 to +40									
Lubrication	Lubricated for lifetime											
Paint	Blue RAL 5002											
Direction of rotation	Motor and gearhead same direction											
Type of protection	IP 65											
Mass moment of inertia (referring to the drive)	J_1	kgcm ²	24	10.24	8.48	8.20	6.90	6.75	6.06	5.98	5.92	5.88
			32	15.83	14.08	13.79	12.49	12.35	11.65	11.58	11.51	11.47
			38	14.36	12.06	12.31	11.02	10.87	10.17	10.10	10.03	10.00
			48	26.41	24.66	24.37	23.07	22.93	22.23	22.16	22.09	22.05
Clamping hub diameter (mm)												

* Binary ratios (32, 64) available as an option. Consult alpha.
 ** For higher ambient temperature, reduce nominal input speed n_{1N} .
 *** In reference to the center of the output shaft.
 **** Measured at ratio $i = 5$ (without load).

Alternative output shaft versions

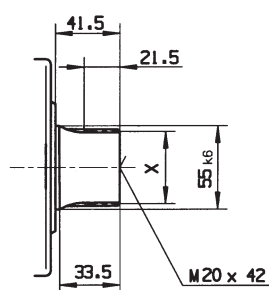
Keywayed output shaft in mm

E = Key to DIN 6885, page 1, form A



Involute gearing DIN 5480 in mm

X = W 55 x 2 x 30 x 26 x 6m, DIN 5480



Conversion table

1 mm	= 0.039 in
1 Nm	= 8.85 in.lb
1 kgcm ²	= 8.85 x 10 ⁻⁴ in.lb.s ²
1 N	= 0.225 lb _f
1 kg	= 2.21 lb _m

SP+ Innovation

Easy error-free motor mounting

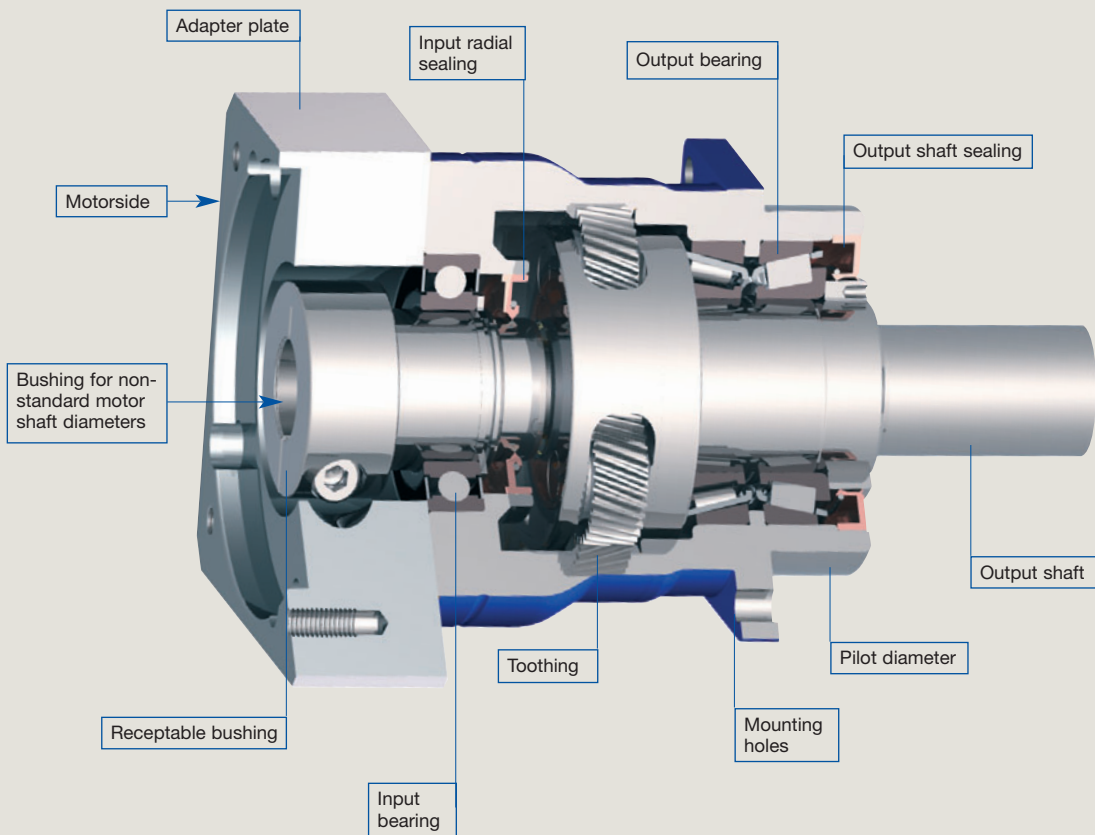
Mounting in a single step by tightening one clamping screw.

Ordering is independent of mounting position

New design eliminates need to specify mounting position on order, reducing error possibilities.

Standard IP65 protection class

Protection from low-pressure water-jets.



Symbols and Index

Symbol	Unit	Designation
C	Nm (in.lb)/arcmin	Rigidity
F	N (lb _f)	Force
i	-	Ratio
j	arcmin	Backlash
J	kgcm ² (in.lb.s ²)	Mass moment of inertia
L	h	Service life
M	Nm (in.lb)	Moment
n	rpm	Speed
η	%	Efficiency
T	Nm (in.lb)	Torque

Index	
capital letters	Permissible values
small letters	Actual values
1	Input
2	Output
A/a	Axial
B/b	Acceleration
h	Hours
K/k	Tilt
m	Mean
Max/max	Maximum
Mot	Motor
N	Nominal
Not/not	Emergency stop
0	No-load running
R/r	Radial
t	Torsional

Quick Selection

The following chart can be used to quickly select a gearhead. However, for best results, we recommend that you utilise the gearhead selection charts in the **alpha Technical Basics** catalog (can be downloaded from www.alphagetriebe.com) or use alpha's **cymex® 3.0** servo/gearhead sizing software to design your drive train.

<p>Cyclic operation S5 Number of cycles ≤ 1000/hour</p> <p>Duty cycle < 60 % and < 20 min.*</p>	<p>1. Using servomotor characteristic data, determine the maximum motor acceleration torque:</p> $T_{\text{MaxMot}} \text{ [Nm (in.lb)]}$ <p>2. Determine maximum acceleration torque at the gearhead output: T_{2b} [Nm]</p> $T_{2b} = T_{\text{MaxMot}} \cdot i \text{ (ratio)}$ <p>3. Compare the maximum acceleration torque just calculated with the permissible acceleration torque (T_{2B}) for the selected gearhead from pages 9-27.</p> <p>Requirement: $T_{2b} \leq T_{2B}$ If not, choose another gearhead.</p>	<p>4. Verify that the clamping hub diameter (table on page 34) is OK for the selected servomotor.</p> <p>5. Compare the motor shaft length, L_{Mot} (mm), with the min. and max. clamping hub depth in the dimensional sketches (pages 8-26).</p>
<p>Continuous operation S1</p> <p>Duty cycle ≥ 60 % or ≥ 20 min.*</p>	<p>1. Calculate after checking for cyclical operation S5.</p> <p>2. Determine the motor nominal torque:</p> $T_{1\text{NMot}} \text{ [Nm (in.lb)]}$ <p>3. Determine the rated load torque at the gearhead output: T_{2n} [Nm]</p> $T_{2n} = T_{1\text{NMot}} \cdot i \text{ (ratio)}$	<p>4. Compare the calculated rated load torque with the permissible rated torque (T_{2n}) for the selected gearhead from pages 9-27.</p> <p>Requirements: $T_{2n} \leq T_{2N}$ If not, choose another gearhead.</p> <p>5. Determine the nominal input speed n_{1n} in rpm and compare with permissible nominal input speed of the gearhead, n_{1N}.</p> <p>Requirements: $n_{1n} \leq n_{1N}$</p> <p>6. Verify proper clamping hub diameter and motor shaft length as in steps 4 & 5 above (S5).</p>

* General guidelines for most applications. Contact alpha if assistance is needed for special cases.

SPclassic 210/240

Size does matter.

Superior positioning accuracy resulting from low torsional backlash and high torsional stiffness.

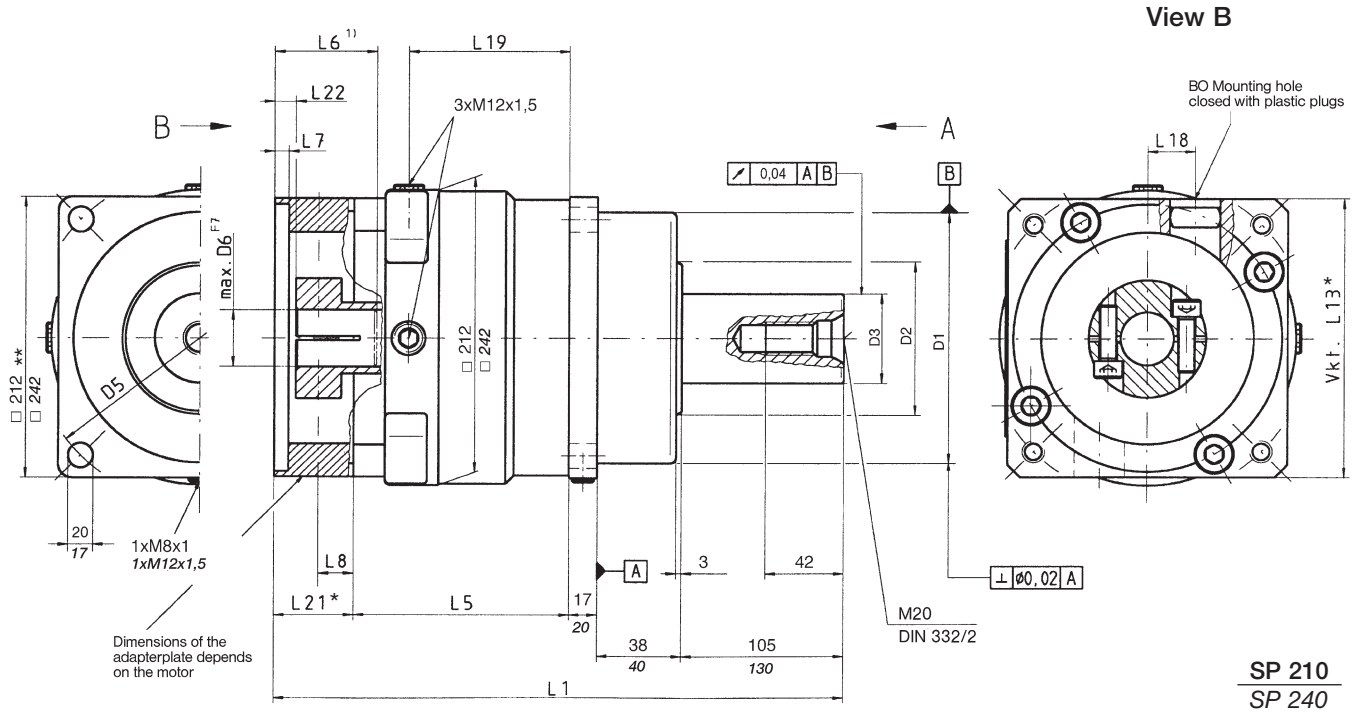
Simple, patented motor mounting with integrated thermal length compensation.

Ideally suited to highly dynamic cyclic S5 (MF) and reliable continuous S1 (MC) operation due to the intelligent design.

Any installation position.

All units have lifelong lubrication.



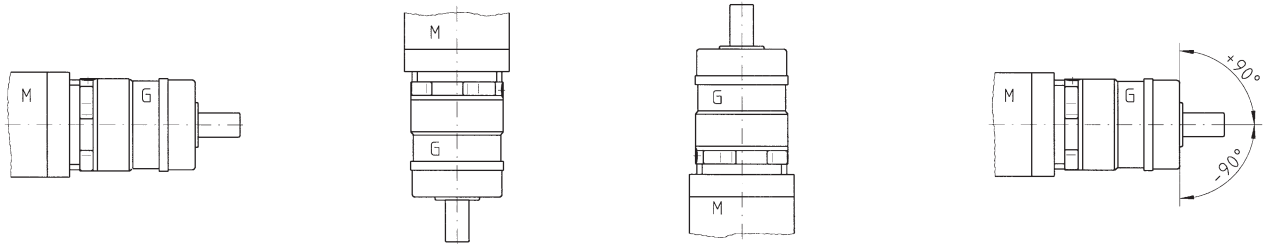


SP 210
SP 240

Dimensions [mm]		D1 g6	D2	D3 k6	D5	D6*	L1*	L5	L6*min	L6*max	L7*	L8	L13*	L18	L19	L21*	L22*
SP 210	1-stage	Ø180	Ø120	Ø75	Ø250	55	350	152.5	45	82	6	13	190	29	114.5	37.5	9.2
	2-stage	Ø180	Ø120	Ø75	Ø250	48	397	199.5	45	82	6	13	190	29	167.5	37.5	9.3
SP 240	1-stage	Ø200	Ø130	Ø85	Ø290	60	436	200	55	110	8	18	260	40	147	46	12.6
	2-stage	Ø200	Ø130	Ø85	Ø290	48	453.5	226	45	82	6	13	190	29	194	37.5	9.3

Dimensions without specified tolerances ±1 mm.
* Dimensions depend on the motor – minimum size listed.
** Additional draft 1.5°

Mounting Position



B5 - horizontal

V1 - vertical
with output shaft
facing downwards

V3 - vertical
with output shaft
facing upwards

S - can be
pivoted ±90° from
the horizontal

M = Motor
G = gearhead

Conversion table	
1 mm	= 0.039 in
1 Nm	= 8.85 in.lb
1 kgcm ²	= 8.85 x 10 ⁻⁴ in.lb.s ²
1 N	= 0.225 lb _f
1 kg	= 2.21 lb _m

Technical Specifications SPclassic 210

MF = Cyclic operation S5
MC = Continuous operation S1

Ratio			1-stage					2-stage							
			3	4	5	7	10	16	20	28	40	50	70	100	
Maximum acceleration torque (max. 1000 cycles per hour)	T_{2B}	Nm	MF	-	1900	1900	1900	1520	1900	1900	1900	1900	1900	1900	1520
			MC	400	630	660	680	750	630	660	680	630	660	680	750
Nominal output torque	T_{2N}	Nm	MF	-	1000	1000	1000	1000	1000	1000	1000	1000	1000	1000	1000
			MC	260	390	420	430	480	390	420	430	390	420	430	480
Emergency stop torque (Permissible 1000 times during the lifespan of the gearhead)	T_{2Not}	Nm	MF	-	4750	4750	4750	3800	4750	4750	4750	4750	4750	4750	3800
			MC	4750											
Nominal input speed (At 20 °C ambient temperature) *	n_{1N}	min ⁻¹	MF	-	1200	1200	1700	1700	2100	2100	2100	2100	2300	2300	2900
			MC	3000	4000	4500	4500	4500	4000	4000	4000	4500	4500	4500	4500
No-load running torque ($n_1=3000$ rpm) (At 20 °C gearhead temperature)	T_{012}	Nm	MF	-	14.5	13.1	11.5	9.0	7.1	6.0	5.4	4.5	3.9	3.6	3.4
			MC												
Maximum input speed	n_{1Max}	min ⁻¹	MF	-	2500	2500	2500	2500	3500	3500	3500	3500	3500	3500	3500
			MC	3400	6000	6000	6000	6000	6000	6000	6000	6000	6000	6000	6000
Torsional backlash	j_t	arcmin	MF	Standard ≤ 4 / Reduced ≤ 2					Standard ≤ 6 / Reduced ≤ 4						
			MC	≤ 4					≤ 6						
Torsional rigidity	C_{t21}	Nm/arcmin		~225					~225						
Max. axial force **	F_{2AMax}	N		22 500					22 500						
Max. radial force **	F_{2RMMax}	N		18 000					18 000						
Max. tilting moment	M_{2KMMax}	Nm		2430					2430						
Efficiency at full load	η	%	MF	≥ 97					≥ 94						
			MC	≥ 98.5					≥ 96.5						
Service life (For calculation, see alpha Technical Basics catalog)	L_h	h	MF	$> 20\ 000$					$> 20\ 000$						
			MC	$> 30\ 000$					$> 30\ 000$						
Weight	m	kg		53					50						
Noise level ($n_1=3000$ rpm)	L_{PA}	dB(A)		≤ 72											
Max. permissible housing temperature		°C		+90											
Ambient temperature		°C		-10 to +40											
Lubrication			MF	Synthetic oil viscosity ISO VG 220											
			MC	Lubricated for lifetime											
Paint				Blue RAL 5002											
Mounting position				Please advise with order											
Direction of rotation				Motor and gearhead same direction											
Type of protection				IP 64											
Mass moment of inertia (referring to the drive)	J_1	kgcm ²	32	-	-	-	-	-	36.3	34.5	32.3	23.1	21.9	20.2	18.9
			38	-	-	-	-	-	37.4	35.6	33.4	24.3	23.0	21.3	20.0
Clamping hub diameter (mm)			48	-	-	-	-	-	42.0	40.2	37.9	28.8	27.6	25.8	24.6
			55	106.3	75.8	63.5	52.9	47.1	-	-	-	-	-	-	-

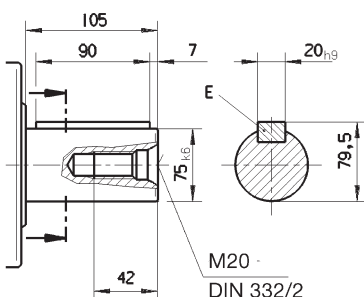
* For higher ambient temperature, reduce nominal input speed n_{1N} .

** In reference to the center of the output shaft.

Alternative SP210: output shaft versions

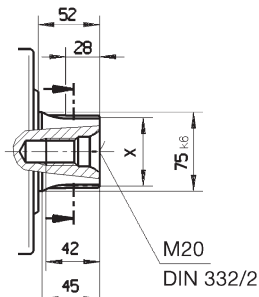
Keywayed output shaft in mm

E = Key to DIN 6885, page 1, form A



Involute gearing DIN 5480 in mm

X = W 70 x 2 x 30 x 34 x 6m, DIN 5480



Technical Specifications **SPclassic 240**

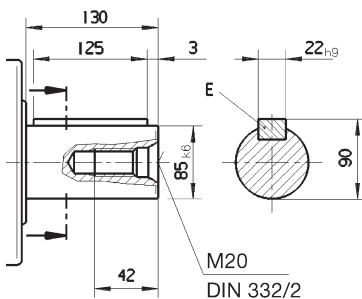
			1-stage					2-stage							
Ratio	i		3	4	5	7	10	16	20	28	40	50	70	100	
Maximum acceleration torque (max. 1000 cycles per hour)	T_{2B}	Nm	MF	-	3400	3400	3400	2720	3400	3400	3400	3400	3400	3400	2720
			MC	670	1000	1050	1100	1200	1000	1050	1100	1000	1050	1100	1200
Nominal output torque	T_{2N}	Nm	MF	-	1700	1700	1700	1700	1700	1700	1700	1700	1700	1700	1700
			MC	430	660	690	720	800	660	690	720	660	690	720	800
Emergency stop torque (Permissible 1000 times during the lifespan of the gearhead)	T_{2Not}	Nm	MF	-	8500	8500	8500	6800	8500	8500	8500	8500	8500	8500	6800
			MC	8500											
Nominal input speed (At 20 °C ambient temperature) *	n_{1N}	min ⁻¹	MF	-	1000	1500	1500	1900	1900	1900	1900	2100	2100	2400	
			MC	3000	3500	4000	4000	4000	3500	3500	3500	4000	4000	4000	4000
No-load running torque ($n_1=3000$ rpm) (At 20 °C gearhead temperature)	T_{012}	Nm	MF	-	20	15	10	7	5	4.3	3.9	3	2.4	2.1	1.9
			MC												
Maximum input speed	n_{1Max}	min ⁻¹	MF	-	2200	2200	2200	2200	3500	3500	3500	3500	3500	3500	3500
			MC	3400	4000	5000	5000	5000	4000	4000	4000	5000	5000	5000	5000
Torsional backlash	j_t	arcmin	MF	Standard ≤ 4 / Reduced ≤ 2					Standard ≤ 6 / Reduced ≤ 4						
			MC	≤ 4					≤ 6						
Torsional rigidity	C_{t21}	Nm/arcmin	~350					~350							
Max. axial force **	F_{2AMax}	N	27 800					27 800							
Max. radial force **	F_{2RMax}	N	27 000					27 000							
Max. tilting moment	M_{2KMMax}	Nm	4226					4226							
Efficiency at full load	η	%	MF	≥ 97					≥ 94						
			MC	≥ 98.5					≥ 96.5						
Service life (For calculation, see alpha Technical Basics catalog)	L_h	h	MF	> 20 000					> 20 000						
			MC	> 30 000					> 30 000						
Weight	m	kg	80					70							
Noise level ($n_1=3000$ rpm)	L_{PA}	dB(A)	≤ 76					≤ 72							
Max. permissible housing temperature		°C	+90												
Ambient temperature		°C	-10 to +40												
Lubrication			MF	Synthetic oil viscosity ISO VG 220											
			MC	Lubricated for lifetime											
Paint			Blue RAL 5002												
Mounting position			Please advise with order												
Direction of rotation			Motor and gearhead same direction												
Type of protection			IP 64												
Mass moment of inertia (referring to the drive)	J_1	kgcm ²	32	-	-	-	-	-	47.3	43.1	37.5	32.4	29.5	24.9	21.4
			38	-	-	-	-	-	48.4	44.2	38.6	33.6	30.6	26.0	22.5
			48	-	-	-	-	-	53.0	48.8	43.2	38.1	35.1	30.6	27.1
			60	229.7	146.3	119.9	96.4	83.1	-	-	-	-	-	-	-
Clamping hub diameter (mm)															

* For higher ambient temperature, reduce nominal input speed n_{1N} .
 ** In reference to the center of the output shaft.

Alternative **SP240**: output shaft versions

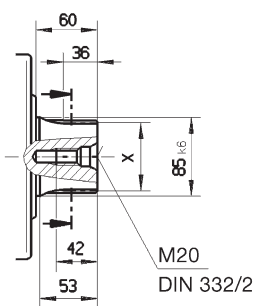
Keywayed output shaft in mm

E = Key to DIN 6885, page 1, form A



Involute gearing DIN 5480 in mm

X = W 80 x 2 x 30 x 38 x 6m. DIN 5480



Conversion table

1 mm	= 0.039 in
1 Nm	= 8.85 in.lb
1 kgcm ²	= 8.85 x 10 ⁻⁴ in.lb.s ²
1 N	= 0.225 lb _f
1 kg	= 2.21 lb _m

Ordering Key

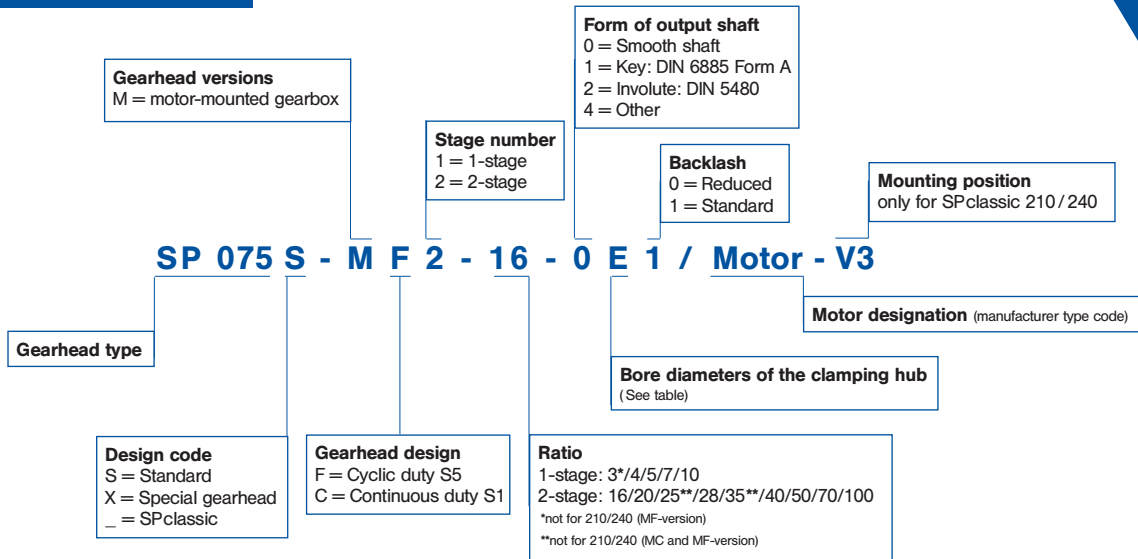


Table of clamping hub diameters for MF version;
 MC version use only diameter in bold

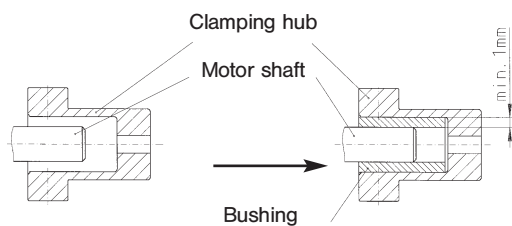
Gearhead stages						SPclassic	
	1 / 2	1 / 2	1 / 2	1 / 2	1 / 2	1 / 2	1 / 2
Motor shaft diameter (mm)*	060	075	100	140	180	210	240
11	B / B	- / B	- / -	-	-	-	-
14	C / C	C / C	- / C	-	-	-	-
19	E / +	E / E	E / E	- / E	-	-	-
24	+	G / +	G / G	G / G	- / G	-	-
28	+	+	H / +	- / -	- / -	-	-
32	+	+	- / +	I / -	- / I	- / 1	- / 1
38	+	+	K / +	K / K	K / K	- / 2	- / 2
48	+	+	+	M / +	M / M	- / 3	- / 3
55	+	+	+	+	+	4 / +	- / +
60	+	+	+	+	+	+	4 / +

- Select next larger character
 + Select next larger gearhead

* If your motor shaft diameter is not listed, add 2 mm to diameter and select next higher size.

Bushing

If the diameters of the motor shaft and the clamping hub do not match, a bushing is used.
 Minimum wall thickness of the bushing is 1 mm.



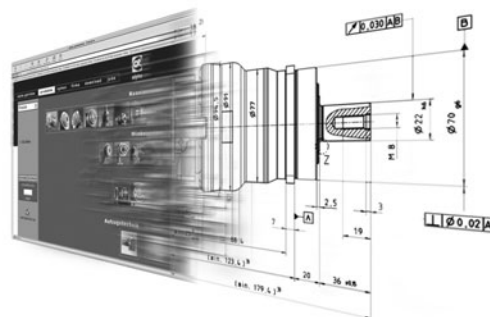
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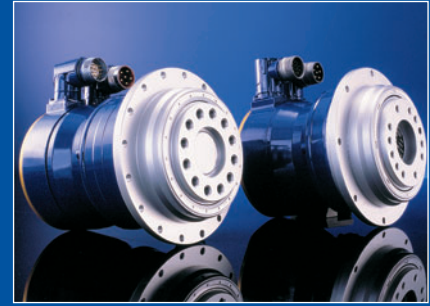
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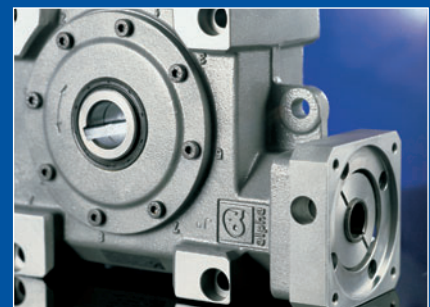
LP+ / LPB+ - Value Line

Economic precision.
Optional with geared pulley mount.
Cyclic and continuous duty operations.
Torsional backlash ≤ 8 arcmin.
Acceleration torque up to 400 Nm.



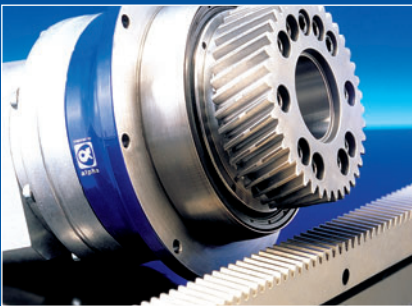
HG+ Hollow-Shaft Precision with shrink-disc

Cyclic and continuous operation operations.
Torsional backlash ≤ 4 arcmin.
Acceleration torque up to 640 Nm.



V - Drive®

Cyclic and continuous duty operations.
Torsional backlash ≤ 3 arcmin.
Acceleration torque up to 718 Nm.
Direct mounting to servo motor.



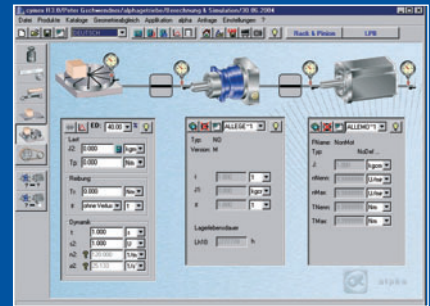
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Metal bellows and safety couplings.
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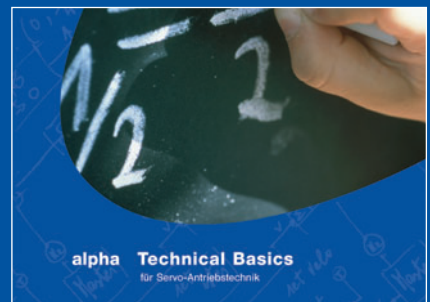
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